ΗΙΟΚΙ

POWER ANALYZER PW3390



High Accuracy Power Analysis. Anywhere, Anytime.

High Accuracy and Mobility. A New Value for Power Analysis.

The original HIOKI POWER ANALYZER 3390, released 8 years ago, featured the latest measurement technology built into a compact casing.

Pair with Hioki current sensors and take them anywhere to immediately make highly accurate measurements.

This was the unique value of the 3390.

Now, Hioki has enhanced this value while refining the measurement technology even further.

Proper accuracy and bandwidth to precisely measure inverter output. Phase shift function for the exact measurement of high frequency, low power factor power. A broad current sensor lineup that expands the range of measurement possibilities.

Refinements that empower you to conduct precise power analysis in any situation.



Complete Pursuit of Measurement Accuracy and High Frequency **Characteristics**

The PW3390 delivers 4 input channels and ±0.04% basic accuracy for power - the top instrument in its class. Achieve more precise measurements of the power and efficiency of high efficiency equipment used in power electronics. Further, a 200 kHz measurement band and flat amplitude and phase characteristics up to high frequencies enable the precise measurement of power at top frequency levels and low power factor.



Power Analysis Engine That Achieves High-Speed Simultaneous Calculation on **5** Systems

Precisely capture input waveforms with 500 kS/s high-speed sampling and a high resolution 16-bit A/D converter. The power analysis engine performs independent digital processing for 5 systems: period detection, wideband power analysis, harmonic analysis, waveform analysis, and noise analysis. High-speed simultaneous calculation processing enables both precise measurements and a 50 ms data refresh rate.



Current Sensors for the Thorough Pursuit of High Accuracy. Achieve Superior Accuracy for High-Frequency, Low Power Factor Power.

High Accuracy Sensor Pass-Through Type

Pass-through type with high accuracy and a wide measurement range. Conduct extremely accurate measurements of large currents to a maximum of 1000 A over a wide operating temperature range.

High Accuracy Sensor Clamp Type

Clamp for quick and easy connections. Conduct extremely accurate measurements of large currents to a maximum of 1000 A over a wide operating temperature range.

High Accuracy Sensor Direct Wire Type

Newly developed DCCT method delivers expansive measurement range and superior measurement accuracy at a rating of 50 A.







Built-in Current Sensor Phase Shift Function

Equipped with new virtual oversampling technology. Achieve phase shift equivalent to 200 MS/s while maintaining a high speed of 500 kS/s, as well as a high resolution of 16 bits. Set and correct the phase error of the current sensor at a resolution of 0.01°. Use of the phase shift function results in a dramatic reduction of measurement error. This allows the measurement of high-frequency, low-power factor power included in the switching frequency of inverter output, which is difficult to measure with conventional equipment.



Virtual oversampling: Technology that uses a sampling frequency several hundred times higher than the actual sampling frequency to perform virtual deskewing

In the Laboratory or in the Field

Take Highly Accurate Measurements Even in Tough Temperature Conditions

Severe temperature environments, such as engine rooms with intense temperature changes and constant temperature rooms, can hinder high accuracy measurements. The extremely accurate pass-through and clamp type sensors both feature excellent temperature characteristics and a wide operation temperature range to help address these challenges.



Max. 6000 A Measurement on 50 Hz/60 Hz Lines

The CT7040 AC FLEXIBLE CURRENT SENSOR series can measure commercial power lines up to 6000 A, including solar power conditioner output. Even thick cables can be wired easily among crowded wiring or in narrow locations.



New Method for Measuring Large Current over Multi-Cable Wiring

Highly accurate measurement of current in multi-cable wiring with large currents has been difficult-until now. The CT9557 adds the output waveforms from the high accuracy sensors connected to each branch line of the multi-cable wiring, for the highly accurate measurement of large currents.



Achieve High Accuracy Measurement Even in the Field

Dramatically compact and light-weight form factor achieved by concentrating the calculation functions in the power analysis engine. Highly accurate measurements normally achieved in the laboratory are now also possible in the field.



External Power Supply Not Needed for Sensor Connections

Power can be supplied to the current sensor from the main unit, so there is no need to provide a separate external power supply for the current sensor. Connected sensors are recognized automatically, for reliable and quick measurements.



Wiring Displays and Quick Setup Lets You Begin Measuring Immediately

Perform wiring while checking wiring diagrams and vectors on the screen. Optimum settings are performed automatically simply by selecting a connection and using the quick setup function.



Extensive Interface for Linking with External Devices

Wide variety of built-in interfaces, including LAN, USB (communication, memory), CF cards, RS-232C, synchronization control, and external control.

D/A output* delivers analog output at 50 ms for up to 16 parameters. The voltage and current waveform** for each channel can also be output.





* Built-in for PW3390-02 and PW3390-03

** During waveform output, accurate reproduction is possible at an output of 500 kS/s and with a sine wave up to 20 kHz.

Switch Screens with a Single Touch, Accessing a Variety of Power Analysis Methods

The power analysis engine allows the simultaneous, parallel calculation of all parameters. Access a variety of analysis methods simply by pressing the page keys to switch screens.



Vector



Confirm the voltage/current/power/phase angle for each harmonic order on a vector graph and as numerical values.

Waveform



Display voltage/current waveforms for 4 channels at a high speed of 500 kS/s or a maximum length of 5 seconds. Waveform data can be saved.

Harmonics Graph



Display harmonics up to the 100th order for voltage/current/power in bar graphs. Confirm the numerical data for the selected order at the same time.

Efficiency and Loss

Vector CH1 CH2 C	налан	4 Wave + Noise Select Effects	Ki Graph Rotor G23-
71	4	85.75	%
72		78.88	%
73		67.64	%
Lossi	3	0.0236k	w
Loss2	3	0.0300k	w
Loss3	-	0.0535k	w

Using active power values and motor power values, confirm efficiency η [%] and loss [W] and total efficiency for each inverter/motor on a single unit at the same time.

Selection Display

Unel	85.01	V.	Unt	85.01	V.	Old Rangel	4 time
Ume2	85.22	v	Us:2	85.22	V.	Ultrane UN	
Une3	84.63	¥ ¥ ¥	Und	84.63	****	I Minis 105	
Unet	480.84	v	Unot	0.38	v		I itimi
Inel	455-18	A.	I and	455.18	A.	CH2 Range	
Irm2	457.12	Α.	In2	457.10	A	Ultanu USV	
Ired.	459.94	A.	Ind:	459.94	A	I Kini UM	16 item
Inef	193.27	A	I Inot.	25.98	Α		
P	22.20k	w	SI	22.30k	A VA	OKS Receiption	-
P2	22.46k	w	52	22.49k	VA.	Ultrana 155	32 11-00
P3	22.50k	w	53	22.56k	VA.	Littlevic 1988	
P4	92.09k	W	54	92.93k	VA.	Oit kings	
#1	74.285	H=	AL.	0.9958		UKana Silv	
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13	74.283	He	1.1	0.9971		• MALINE MADE	
00001001	0.0000	He	M	0.9909			Select

Select 4/8/16/32 display parameters individually for each screen, and summarize them on a single screen.





Display FFT results for voltage and current as graphs and numerical values, up to a maximum of 100 kHz. This is perfect for the frequency analysis of inverter noise.

Power

Vector CH		H2ICH5 CH	14 line			Efficiency XI (1	(B)
Him: DT	923	KON Spine Bill	dt Rom	TEV In	feral)	TOA OFF	iii:	54	(Farthers)
Ueni Uen2 Uen3		160.68	N N N	31 42 33		54.04k 54.45k 54.57k	VA.		Power
0m(23		160.51	A.	8123		163.06k	A.V		Integration
1 read 1 read		513.64	\$	- 11 - 12		27.58k			
I read I read	4	519.58	2	03 01 21		27.29k 02.41k			Valtage
1222		46.47k 46.97k 47.25k	ar ar	41 42 43		30.69 30.38 30.01			Cerest.
P123		140.69k		#123		30.36			Herenica Gright
A1 A2 A5 A123		0.8599 0.8627 0.8659 0.8659		11 12 13		151.27 151.11 151.26	Ha Ha Ha		Heronica List

On the basic measurement screen, display voltage/current/power/power factor/frequency and other parameters in a list for each connection.

X-Y Graph



Create inverter characteristic evaluations and motor torque maps. Select the desired parameter to display an X-Y plot graph.

Applications

Measure the Power Conversion Efficiency of Inverters



Key features

- Isolated input of voltage and current on each of 4 channels for simultaneous measurement of the primary and secondary power of inverters
- Simultaneous measurement of all important parameters for secondary analysis of inverters, such as RMS value, MEAN value, and fundamental components
- Easy wiring with current sensors. Reliable confirmation of wiring with vector diagrams
- Current sensors reduce effects of common mode noise from inverters during power measurement
- Simultaneous measurement of noise components, in addition to the harmonic analysis required for the measurement of inverter control

Highly Accurate and Fast 50 ms Calculation of Power in Transient State

Measure power transient states, including motor operations such as starting and accelerating, at 50 ms refresh rates. Automatically measure and keep up with power with fluctuating frequencies, from a minimum of 0.5 Hz.



Automatic detection of fundamental wave even if the frequency fluctuates, from low to high frequencies

Measure High-Frequency Noise in Inverters

Power supply problems caused by high switching inverter frequencies are unrelated to the fundamental frequency, making it difficult to conduct proper harmonic analysis. The noise analysis function performs a frequency analysis of noise components up to 100 kHz, and displays the frequency, and voltage and current levels for the top 10 points. This is effective for measuring high-frequency noise in inverters.



Combined Accuracy of Current Sensors Applicable throughout Entire Range

Combined accuracy throughout the entire range is provided through the use of a built-to-order high accuracy pass-through type current sensor. Obtain highly accurate measurements regardless of range, from large to minute currents, even for loads that fluctuate greatly.

Legacy Model 3390



Combination of 3390 and 9709 (500 A rating) Total Accuracy when measuring currency of 45 to 66 Hz and f.s. for each range



Combination of PW3390 and the high accuracy 9709-05* (500 A rating, built-to-order) Total accuracy when measuring currency of 45 to 66 Hz and f.s. for each range

* High-accuracy specifications are not defined for the built-to-order high accuracy current sensor when used alone.

Acquire Data from up to 8 Synchronized Units (32 Channels)

When you connect CONNECTION CABLE 9683 to multiple PW3390 units, the control signals and internal clocks synchronize. From the master unit, you can control the measurement timing on the PW3390 units that are set as slaves. With interval measurement, you can save synchronized measurement data to a CF card or a PC to achieve simultaneous measurements across a larger number of systems.



Analyze and Measure EV/HEV Inverter Motors



Key features

- Easy wiring and highly accurate measurements with the use of a pass-through type current sensor
- Simultaneous measurement of all important parameters for secondary analysis of inverters, such as RMS value, MEAN value, and fundamental components
- 3. 0.5 Hz to 5 kHz harmonic analysis without external clock
- Total measurement of inverter motors with built-in motor analysis function
- Measurement of the voltage, torque, rotation rate, frequency, slip, and motor power required for motor analysis with a single unit
- More precise measurements of electrical angle with incremental type encoders

Electric Angle Measurement of Motors (PW3390-03 only)

The PW3390-03 features a built-in electric angle measurement function required for vector control via dq coordinate systems in high-efficiency synchronized motors. Make real-time measurements of phase angles for voltage and current fundamental wave components based on encoder pulses. Further, zero-adjustment of the phase angle when induced voltage occurs allows electric angle measurement based on the inductive voltage phase. Electric angle can also be used as an Ld and Lq calculation parameter for synchronized motors.



Display motor electric angles on the vector screen

Measure Harmonics with Consideration for PWM Waveform Characteristics

The zero-crossing filter automatically matches the input frequency in the range of 0.5 Hz to 5 kHz to reliably detect the fundamental frequency. Further, harmonic analysis that is based on the fundamental frequency automatically prevents aliasing error using a digital AAF, which allows both precision and measurement reproducibility at a high level.





Motor analysis screen (Torque, rotation rate, motor power, slip) For CH B, enter the Z-phase pulse of the encoder to measure electric angle, and enter the B-phase pulse to measure rotation direction.

Transfer to Data Logger via Bluetooth[®] wireless technology

Connect the PW3390 and a data logger (with support of LR8410 Link) via Bluetooth[®] wireless technology to wirelessly transmit 8 parameters of measurement values from the PW3390 to the data logger. In addition to the voltage, temperature, humidity, and other parameters measured by the multichannel data logger, you can also integrate the measurement values of the PW3390 and observe and record them in real time.



* Connection requires the serial - (Bluetooth[®] wireless technology) conversion adapter and power supply adapter recommended by Hioki. Please inquire with your Hioki distributor.

Measure the Efficiency of PV Power Conditioners (PCS)



Key features

- 4 built-in channels, standard. Simultaneously measure the I/O characteristics of power conditioners.
- Current sensors can measure even large currents with high accuracy. Reliable confirmation of wiring with vector diagrams.
- Measure the amount of power sold/ purchased from power conditioner output on interconnected systems with a single unit.
- DC mode integration function, which responds quickly to input fluctuations such as with solar power, built in.
- Measure ripple factor, efficiency, loss, and all other parameters that are required for the measurement of power conditioners for solar power with a single unit.

HIOKI's Current Measurement Solutions for Large Currents of 1000 A or More

Introducing a lineup of sensors taking measurements up to 6000 A for 50 Hz/60 Hz, and up to 2000 A for direct current. The CT9557 SENSOR UNIT lets you add the output waveforms from multiple high accuracy sensors. Use multi-cable wiring lines to take highly accurate measurements of up to 4000 A.

			Blue: High accuracy sensor	Black: Normal sensors		
curren	mended t sensor ement target	DC power	System power 50 Hz/60 Hz	Inverter secondary power		CT6865-05 (AC/DC 1000 A) Pass-through type; Wideband, high accuracy
1000 A or less			CT6865-05 or CT6846-05	1	-	CT6846-05 (AC/DC 1000 A) Easy-connect clamp type CT9557
	1-cable wiring	CT7742	CT7642	-	1111	Add waveforms from multiple current sensors
2000 A or less	2-cable wiring	CT9557 +	CT6865-05 x 2 or CT9557 + CT6	846-05 x 2	<u></u>	CT7742 (AC/DC 2000 A) Stable measurement of DC without zero
4000 A or loop	Less than 4-cable wiring	-	CT7044/CT7045/CT7046	-	~	offset CT7642 (AC/DC 2000 A)
4000 A of less	4-cable wiring		CT6865-05 x 4 or CT9557 + CT6	846-05 × 4	× 4	Wider frequency characteristics than the CT7742
6000 A or less		-	CT7044/CT7045/CT7046	-		CT7044/ CT7045/ CT7046 (AC 6000 A) Flexible, for easy connections even in narrow gaps

Support for PCS Parameters

Simultaneously display the parameters required for PCS, such as efficiency, loss, DC ripple factor, and 3-phase unbalance rate. Easily check the required measured items for improved test efficiency. By matching the measurement synchronization source for both input and output, you can perform DC power measurements that are synchronized with the output AC as well as stable efficiency measurements.

P ₄		8.396k	W	C
P 123		7.850k	W	З
71		93.498	X	C
U _{rf4}	5	0.212	X	F
f ₁		50.319	H	F
$U_{\rm thdl}$		2.390	X	١
U _{wb}		0.306	X	ι
Loui		0.546k	W	L

DC power (panel output)
 3-phase power (PCS output)
 Conversion efficiency
 Ripple factor
 Frequency
 Voltage total harmonic distortion
 Unbalance rate
 Loss

±0.01 Hz^{*} Basic Accuracy for Voltage Frequency Measurements

Perform the frequency measurements that are required for various PCS tests with industry-leading accuracy and stability. Take highly accurate frequency measurements on up to 4 channels simultaneously, while also measuring other parameters at the same time.



^{*} If you require even higher accuracy for frequency, please inquire with your local Hioki distributor.

Test Automobile Fuel Economy



Key features

- 1. Accurately measure recharge and discharge power with excellent basic accuracy and DC accuracy.
- 4 built-in channels, standard. Support for multiple recharge and discharge measurements, including auxiliary batteries.
- Easily achieve highly accurate measurements with clamp sensors, which can be used in a wide range of operating temperatures.
- Easily link with other measuring instruments through integration control with an external control interface.

Evaluate WLTC Mode Performance - A New Fuel Economy Standard

Taking fuel economy measurements that comply with WLTP international standards requires the precise measurement of current integration and power integration for the recharging/ discharging of each battery in the system. High accuracy clamp current sensors, the excellent DC accuracy of the PW3390, and the ability to integrate current and power at 50 ms intervals are extremely effective in meeting this application.



Current and Power Integration Function by Polarity

DC integration measurement integrates the recharging power and discharging power by polarity for every sample at 500 kS/s, and measures positive-direction power magnitude, negative-direction power magnitude, and the sum of positive- and negative-direction power magnitude during the integration period. Accurate measurement of recharging power and discharging power is possible even if there is rapid repetition of battery recharging/discharging.



Optimal Current Sensors for Automotive Testing

Easily connect high accuracy clamp-type sensors without cutting the cables. Sensors operate over a temperature range of -40°C to 85°C (-40°F to 185°F), characteristics that enable highly accurate measurements even inside the engine room of a car.



Link to Peripheral Devices via External Control

Use external control terminals to START/STOP integration and capture screen shots. This makes it easy to control operations from console switches and link to the timing of other instruments when measuring the performance of an actual automobile.



External Appearance



Software

Download software, drivers, and the Communications Command Instruction Manual from the Hioki website. https://www.hioki.com

"PW Communicator" PC Communication Software

PW Communicator is an application program for communicating between a PW3390 series power analyzer and a PC. It includes many useful functions, such as configuring PW3390 settings, monitoring measurement values, saving CSV data, and calculating efficiency.

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LabVIEW Driver

Obtain data and configure measurement systems with the LabVIEW driver.

* LabVIEW is a registered trademark of NATIONAL INSTRUMENTS.

Specifications

Basic Specifications

Accuracy guaranteed for 6 months (and 1.25 times speci-fied accuracy for one year) Post-adjustment accuracy guaranteed for: 6 months ations

Measurement line type	Single-phase 2-	wire (1P2W), Sir	ngle-phase 3-wir	e (1P3W), 3-pha	se 3-wire
	(3P3W2M, 3P3V			СНЗ	CH4
	Pattern 1	1P2W	1P2W	1P2W	1P2W
	Pattern 2		3W	1P2W	1P2W
	Pattern 3		W2M	1P2W	1P2W
	Pattern 4 Pattern 5		3W W2M	1P: 1P:	
	Pattern 6		W2M	3P3\	
	Pattern 7		3P3W3M		1P2W
Number of input	Pattern 8 Voltage: 4 chanr		3P4W		1P2W
channels Measurement input	Current: 4 chanr Voltage: Plug-in	jacks (safety jac	cks) nectors (ME15W)		
terminal type Input methods	Voltage: Isolated	d inputs, resistiv	. ,	it)	
Voltage range	15 V/30 V/60 V/1	50 V/300 V/600			able.)
Current range	2 A/4 A/8 A/20 A		ining oyotom. A	-	9272-05, 20 A)
(): Sensor used	0.4 A/0.8 A/2 A/4 4 A/8 A/20 A/40 4 A/80 A/200 A	A/80 A/200 A (/400 A/800 A/2 A/1 A/2 A/5 A (/20 A/50 A 100 A/200 A/50 /200 A/400 A/1 A A/4 kA/8 kA A/4 kA/8 kA/20 A/80 A/200 A A/80 A/200 A	0 A kA kA	(200 A set (2000 A set (5 A sens) (50 A set (500 A set) (500	sensor) sor) isor) ensor) ensor) and CT7742) , CT7045, 246) A sensor) sensor) sensor) A sensor)
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Crest factor	300 (relative to r 3 (relative to vol	ninimum effectiv tage/current ran	ve voltage/curren ge rating) (for 15	t input) (for 1500 00 V range: 1.33) V range: 133))
Input resistance (50 Hz/60 Hz)	Voltage input sec Current sensor in		: 2 MΩ ±40 kΩ (dif : 1 MΩ ±50 kΩ	ferential input and	d insulated input
Maximum input voltage	Voltage input se Current sensor i		1500 V, ±2000 \ 5 V, ±10 Vpeak	/peak	
Maximum rated voltage to earth		ategories III 600	0 Hz/60 Hz) V (anticipated tra V (anticipated tr		
Measurement method	zero-crossing ca		f voltage and cur d	rent, simultaneo	us
Sampling	500 kHz/16 bit				
Measurement frequency range	DC, 0.5 Hz to 20	10 kHz			
Synchronization frequency range	0.5 Hz to 5 kHz Selectable lower	limit measureme	ent frequency (0.5	Hz/1 Hz/2 Hz/5	Hz/10 Hz/20 Hz
Synchronization source	pulse input), DC (50 ms or 10 Selectable for ea the same synchr The zero-crossin Two filter levels (Operation and ac	0 ms fixed) ach measuremen onization source g filter automatic strong or mild) curacy are undete ccuracy are dete	notor evaluation ir nt channel (U/I for e) ally matches the d ermined when the c ermined when U c	each channel m igital LPF when L zero-crossing filte	easured using I or I is selected. r is disabled (off)
Data update interval	50 ms				
LPF	500 Hz: Accurac 5 kHz: Accuracy	y defined at 60 defined at 500	ectable for each Hz or below (Ado Hz or below) kHz or below (A	±0.1% f.s.)	above 10 kHz)
Zero-crossing filter	Off, mild or stror	ng			
Polarity discrimination	Voltage/current		ming comparison digital LPF	method	
Basic measurement parameters	AC component, v voltage waveform voltage ripple fac rectification RMS fundamental wav -, current total has active power, app current phase an negative-direction magnitude, positi	oltage simple ave peak +, voltage unbai equivalent, curre e component, cu rmonic distortion, arent power, rea gle, power phase n current magnitu ve-direction pow	mean value rectifiin erage, voltage fun waveform peak -, lance factor, RMS ant AC component rrent waveform per current ripple fac ctive power, powe angle, positive-di dde, sum of positiv et magnitude, neg ction power magn	damental wave co voltage total harm current, current m , current simple a ak +, current wav tor, current unbala f factor, voltage p rection current m e- and negative-c ative-direction pc	omponent, nonic distortion, nean value verage, current eform peak ance factor, hase angle agnitude, tirection current wer magnitude,
		m, motor power	slin		
Voltage/current rectification method		tage and curren	t values to use fo	r calculating ap	parent and

	Voltage (U)	Current (I)
DC	±0.05% rdg. ±0.07% f.s.	±0.05% rdg. ±0.07% f.s.
$0.5 \text{ Hz} \le f < 30 \text{ Hz}$	±0.05% rdg. ±0.1% f.s.	±0.05% rdg. ±0.1% f.s.
		±0.05% rdg. ±0.1% f.s. ±0.04% rdg. ±0.05% f.s.
66 Hz < f ≤ 1 kHz	±0.1% rdg. ±0.1% f.s.	±0.1% rdg. ±0.1% f.s.
1 kHz < f ≤ 10 kHz	±0.2% rdg. ±0.1% f.s.	±0.2% rdg. ±0.1% f.s.
10 kHz < f ≤ 50 kHz	±0.3% rdg. ±0.2% f.s.	±0.3% rdg. ±0.2% f.s.
		±1.0% rdg. ±0.3% f.s.
100 KHZ < I ≤ 200 kl		±20% f.s. Phase difference
DC		-
0.5 Hz ≤ f < 30 Hz	±0.05% rdg. ±0.1% f.s.	±0.08°
30 Hz ≤ f < 45 Hz	±0.05% rdg. ±0.1% f.s.	±0.08°
45 Hz ≤ f ≤ 66 Hz	±0.04% rdg. ±0.05% f.s.	±0.08°
$66 \text{ Hz} < f \le 1 \text{ kHz}$	±0.1% rdg. ±0.1% f.s.	±0.08°
	-	±(0.06*f+0.02)° ±0.62°
	-	±(0.005*f+0.4)°
L	Hz ±20% f.s.	±(0.022*f-1.3)°
		r Udc and Idc. while accuracy
figures for frequencies of	other than DC are defined for Urms	and Irms.
		ed for full-scale input with a
Accuracy figures for ve	oltage and active power values in	n excess of 220 V in the
Accuracy figures for ve	oltage and active power values ir	n excess of 750 V in the
frequency range of 30	kHz to 100 kHz are provided as	reference values.
the frequency range of	100 kHz to 200 kHz are provided a	as reference values.
		excess of 1000 V are
Accuracy figures for p	hase difference values outside th	ne frequency range of 45 Hz
For voltages in excess	of 600 V, add the following to th	e phase difference accuracy
20 kHz < f ≤ 200 kHz	z:±1°	iracy (at 2 V fs)
		acy figures for current, activ
		ely for the current
		Active power (P)
DC		±0.07% rdg. ±0.077% f.s.
45 Hz ≤ f ≤ 66 Hz		±0.06% rdg. ±0.055% f.s.
Add ±0.12% f.s. (f.s. = F	PW3390 range) when using 1 A or	2 A range.
high-accuracy 9709-0	05, high-accuracy CT6862-05,	or high-accuracy CT6863-
		Active power (P)
DC		±0.095% rdg. ±0.08% f.s.
45 Hz ≤ f ≤ 66 Hz	±0.085% rdg. ±0.06% f.s. =	±0.085% rdg. ±0.06% f.s.
Temperature and hun 80% R.H. or less Warm-up time: 30 mil Input: Within the spec with the sync so zero ground vo adjustment and	cified ranges when the fundame ource, for sine wave input, pow Itage, within effective measure d within the range in which the f	23°C ±3°C (73°F ±5°F), ental wave is synchronized er factor of one, or DC input ment range after zero-
Temperature and hun 80% R.H. or less Warm-up time: 30 mil Input: Within the spec with the sync si zero ground vo adjustment and the synchronizi	nidity for guaranteed accuracy: n. or more cified ranges when the fundame ource, for sine wave input, pow ltage, within effective measure	23°C ±3°C (73°F ±5°F), ental wave is synchronized er factor of one, or DC input ment range after zero-
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Temperature and hun 80% R.H. or less Warm-up time: 30 mil Input: Within the spnce with the sync.s zero ground vo adjustment and the synchronizi ±0.01% f.s./7C (for DC ±0.01% f.s./7C (for DC ±0.01% f.s. or less (wit measurement] acks ar ±1% f.s. or less (wit measurement] acks ar ±1% f.s. or less (wit of 3. v, current and ac where f.s. current is t f.s. active power equa current sensor @10 V/m, current and shere f.s. current is t f.s. active power equa current sensor @10 V/m, current and t.s. active power equa current sensor Voltage, Current, Pow Voltage, Current, Pow Voltage, Current, Pow Voltage, Current, Pow Voltage, Zero-adjustr Within ±300% of eacl Within ±2% f.s. of vol Surement Specifit Four (f1 to f4) Select UJ/ for each m Reciprocal method +	nidity for guaranteed accuracy: n. or more ified ranges when the fundame ource, for sine wave input, pow Itage, within effective measurer attion source conditions 2, add 40.01% f.s. ^{PC}) th 1000 V @50 Hz/60 Hz applied id 0chassis) 10 A/m magnetic field, DC and 5 ±(1-cos (\$+Phase difference a .(\$+Phase difference accuracy the rated primary-side current o als the voltage range x the rate d active power not more than ±6% he rated primary-side current o als the voltage range x the rate d active power not more than ±6% he rated primary-side current o als the voltage range x the rate wer: 1% to 110% of the range wer: from zero-suppression rang or 0.5% f.s. values may be displayed even nent compensation of input offsed h voltage and current display accura cations easurement channel zero-crossing sample value co	23°C ±3°C (73°F ±5°F), ental wave is synchronized er factor of one, or DC input ment range after zero- undamental wave satisfies between voltage 50 Hz/60 Hz) ccuracy//cos(\$) ×100% rdg > ×100% f.s. .s., ft the current sensor d primary-side current of the 3% f.s., ft he current sensor d primary-side current of the ge setting to 120% with no measurement input offset at or below ±10% f.s. ±4 mV acc
Temperature and hun 80% R.H. or less Warm-up time: 30 mil Input: Within the spnce with the sync.s zero ground vo adjustment and the synchronizi ±0.01% f.s./7C (for DC ±0.01% f.s./7C (for DC ±0.01% f.s. or less (wit measurement] acks ar ±1% f.s. or less (wit measurement] acks ar ±1% f.s. or less (wit of 3. v, current and ac where f.s. current is t f.s. active power equa current sensor @10 V/m, current and shere f.s. current is t f.s. active power equa current sensor @10 V/m, current and t.s. active power equa current sensor Voltage, Current, Pow Voltage, Current, Pow Voltage, Current, Pow Voltage, Current, Pow Voltage, Zero-adjustr Within ±300% of eacl Within ±2% f.s. of vol Surement Specifit Four (f1 to f4) Select UJ/ for each m Reciprocal method +	nidity for guaranteed accuracy: n. or more ified ranges when the fundame ource, for sine wave input, pow Itage, within effective measurer d within the range in which the f ation source conditions 2, add 40.01% f.s./°C) th 1000 V @50 Hz/60 Hz applied d chassis) 10 A/m magnetic field, DC and f ±(1-cos (φ+Phase difference a (g+Phase difference a ccuracy) the rated primary-side current o als the voltage range x the rater the rated primary-side current o als the voltage range x the rater the rated primary-side current o als the voltage range x the rater wer: 1% to 110% of the range wer. from zero-suppression ran- ro 15% f.s. values may be displayed even nent compensation of internal 0 the voltage and current range tage and current display accura cations easurement channel zero-crossing sample value co n0.5 Hz to 5 kHz (with "0.0000 Hz" co	23°C ±3°C (73°F ±5°F), ental wave is synchronized er factor of one, or DC input ment range after zero- undamental wave satisfies between voltage 50 Hz/60 Hz) ccuracy//cos(\$) ×100% rdg > ×100% f.s. .s., ft the current sensor d primary-side current of the 3% f.s., ft he current sensor d primary-side current of the ge setting to 120% with no measurement input offset at or below ±10% f.s. ±4 mV acc
Temperature and hun 80% R.H. or less Warm-up time: 30 mil Input: Within the spnce with the sync.s zero ground vo adjustment and the synchronizi ±0.01% f.s./°C (for DU ±0.01% f.s./°C (for DU ±0.01% f.s. or less (with measurement jacks ar ±1% f.s. or less (in 40 Other than Φ = ±90°: When Φ = ±90°: acoos @3 V, current and ac where f.s. current is t f.s. active power eque current sensor @10 V/m, current and f.s. active power eque current sensor @10 V/m, current and t.s. active power eque current sensor @10 V/m, current and f.s. active power eque current sensor Voltage, Current, Pov Voltage, Current, Pov Voltage, Current, Pov Voltage: Zero-adjustr Within ±300% of eacl Within ±2% f.s. of vol surement Specifit Four (f1 to f4) Select UJI for each m Reciprocal method + Synchronous range from 0.5 Hz/1 Hz/2 Hz/5 H	nidity for guaranteed accuracy: n. or more ified ranges when the fundame ource, for sine wave input, pow Itage, within effective measurer attion source conditions 2, add ±0.01% f.s. ^{p.C}) th 1000 V @50 Hz/60 Hz applied ad chassis) 10 A/m magnetic field, DC and f ±(1-cos (\$+Phase difference a (\$+Phase difference a ccuracy the rated primary-side current o als the voltage range x the rate d active power not more than ±6% he rated primary-side current o als the voltage range x the rate ver: 1% to 110% of the range ver: from zero-suppression rang or 0.5% f.s. values may be displayed even nent compensation of input offsed h voltage and current range tage and current display accura cations easurement channel zero-crossing sample value co 0.5 Hz to 5 KHz (with "0.0000 Hz" o z/10 Hz/20 Hz	23°C ±3°C (73°F ±5°F), ental wave is synchronized entator of one, or DC input ment range after zero- undamental wave satisfies between voltage 50 Hz/60 Hz) ccuracy/cos(\$) ×100% rdg > ×100% f.s. .s., ft he current sensor d primary-side current of the 5% f.s., ft he current sensor d primary-side current of the ge setting to 120% with no measurement input offset at or below ±10% f.s. ±4 mV acy rrection r* Hz* unmeasurable time)
Temperature and hun 80% R.H. or less Warm-up time: 30 mil Input: Within the spnce zero ground vo adjustment and the synchroniz ±0.01% f.s./7C (for DU ±0.01% f.s./7C (for DU ±0.01% f.s./7C (for DU ±0.01% f.s. or less (with measurement) jacks ar ±1% f.s. or less (with measurement) jacks ar ±1% f.s. or less (with easurement) jacks ar ±1% f.s. or less (with measurement) jacks ar ±1% f.s. or less (with measurement) jacks ar ±1% f.s. or less (with measurement) jacks ar where f.s. current is th f.s. active power equa current sensor Voltage, Current, Pow Voltage, Current, Pow Voltage, Current, Pow Voltage, Current, Pow Voltage, Current, Pow Voltage, Current, Sof Voltage, Current, Sof Voltage, Current Within ±300% of eacl Within ±2% f.s. of vol Surement Specific Four (f1 to 14) Select U/I for each m Reciprocal method + Synchronous range from 0.5 Hz/1 Hz/2 Hz/5 H 50 ms (measurement)	nidity for guaranteed accuracy: n. or more ified ranges when the fundame ource, for sine wave input, pow Itage, within effective measurer d within the range in which the f ation source conditions 2, add 40.01% f.s./°C) th 1000 V @50 Hz/60 Hz applied d chassis) 10 A/m magnetic field, DC and f ±(1-cos (φ+Phase difference a (g+Phase difference a ccuracy) the rated primary-side current o als the voltage range x the rater the rated primary-side current o als the voltage range x the rater the rated primary-side current o als the voltage range x the rater wer: 1% to 110% of the range wer. from zero-suppression ran- ro 15% f.s. values may be displayed even nent compensation of internal 0 the voltage and current range tage and current display accura cations easurement channel zero-crossing sample value co n0.5 Hz to 5 kHz (with "0.0000 Hz" co	23°C ±3°C (73°F ±5°F), ental wave is synchronized er factor of one, or DC input ment range after zero- undamental wave satisfies between voltage io Hz/60 Hz) ccuracy//cos(\$) ×100% rdg > ×100% f.s. f the current sensor d primary-side current of the 5% f.s., f the current sensor d primary-side current of the iffset at or below ±10% f.s. ±4 mV acy errection pr* Hz* unmeasurable time) : and below)
Temperature and hun 80% R.H. or less Warm-up time: 30 mil Input: Within the spnce with the sync sr zero ground vo adjustment and the synchronizi ±0.01% f.s./rC (for DU ±0.01% f.s./rC (for DU ±0.01% f.s. or less (with measurement jacks ar ±1% f.s. or less (with easurement jacks ar where f.s. current is ti f.s. active power equa current sensor @10 V/m, current and where f.s. current is ti f.s. active power equa current sensor Voltage, Current, Pow Voltage, Current, Pow Voltage, Current, Pow Voltage, Current, Pow Voltage, Current, Soft Voltage, Current, Soft Suerement Specifit Four (f1 to f4) Select UJ/ for each m Reciprocal method + Synchronous range from 0.5 Hz/1 Hz/2 Hz/5 H	nidity for guaranteed accuracy: n. or more ified ranges when the fundame ource, for sine wave input, pow Itage, within effective measure within the range in which the f ation source conditions 2, add ±0.01% f.s./°C) th 1000 V @50 Hz/60 Hz applied d chassis) 0 A/m magnetic field, DC and £ ±(1-cos (φ+Phase difference a ((φ+Phase difference a ccuracy two power not more than ±6% he rated primary-side current o als the voltage range × the rate d active power not more than ±6% he rated primary-side current o als the voltage range × the rate d active power not more than ±6% he rated primary-side current o als the voltage range × the rate wer: from zero-suppression ranger ver: from zero-suppression ranger the tompensation of input offset h voltage and current range tage and current display accuracy cations easurement channel zero-crossing sample value co 10.5 Hz to 5 kHz (with *0.0000 Hz* 2/10 Hz/20 Hz	23°C ±3°C (73°F ±5°F), ental wave is synchronized er factor of one, or DC input ment range after zero- undamental wave satisfies between voltage io Hz/60 Hz) ccuracy//cos(\$) ×100% rdg > ×100% f.s. .s. ft the current sensor d primary-side current of the is% f.s., it the current sensor d primary-side current of the ge setting to 120% with no measurement input offset at or below ±10% f.s. ±4 mV http://sis.s. ±10% f.s. ±4 mV accy
	$\begin{array}{c} 0.5 \mbox{ Hz } \le f < 30 \mbox{ Hz } \le f < 45 \mbox{ Hz } \\ 30 \mbox{ Hz } \le f < 45 \mbox{ Hz } \\ 45 \mbox{ Hz } \le f \le 66 \mbox{ Hz } \\ 11 \mbox{ Hz } \le f \le 66 \mbox{ Hz } \\ 11 \mbox{ Hz } \le f \le 100 \mbox{ Hz } \\ 10 \mbox{ Hz } \le f \le 50 \mbox{ Hz } \\ 50 \mbox{ Hz } \le f \le 50 \mbox{ Hz } \\ 50 \mbox{ Hz } \le f \le 30 \mbox{ Hz } \\ 30 \mbox{ Hz } \le f \le 30 \mbox{ Hz } \\ 30 \mbox{ Hz } \le f \le 30 \mbox{ Hz } \\ 30 \mbox{ Hz } \le f \le 30 \mbox{ Hz } \\ 50 \mbox{ Hz } \le f \le 30 \mbox{ Hz } \\ 50 \mbox{ Hz } \le f \le 60 \mbox{ Hz } \\ 50 \mbox{ Hz } \le f \le 60 \mbox{ Hz } \\ 50 \mbox{ Hz } \le f \le 50 \mbox{ Hz } \\ 50 \mbox{ Hz } \le f \le 30 \mbox{ Hz } \\ 100 \mbox{ Hz } \le f \le 30 \mbox{ Hz } \\ 100 \mbox{ Hz } \le f \le 30 \mbox{ Hz } \\ 100 \mbox{ Hz } \le f \le 30 \mbox{ Hz } \\ 100 \mbox{ Hz } \le f \le 30 \mbox{ Hz } \\ 100 \mbox{ Hz } \le f \le 200 \mbox{ Hz } \\ 30 \mbox{ Hz } \le f \le 200 \mbox{ Hz } \\ 30 \mbox{ Hz } \le f \le 200 \mbox{ Hz } \\ 30 \mbox{ Hz } \le f \le 200 \mbox{ Hz } \\ 30 \mbox{ Hz } \le 1 \le 200 \mbox{ Hz } \\ 30 \mbox{ Hz } \le 1 \le 200 \mbox{ Hz } \\ 30 \mbox{ Hz } \le 200 \mbox{ Hz } \\ 30 \mbox{ Hz } \le 1 \le 200 \mbox{ Hz } \\ 30 \mbox{ Hz } \le 1 \le 200 \mbox{ Hz } \\ 30 \mbox{ Hz } \le 1 \le 200 \mbox{ Hz } \\ 30 \mbox{ Hz } \le 1 \le 200 \mbox{ Hz } \\ 30 \mbox{ Hz } \le 1 \le 200 \mbox{ Hz } \\ 30 \mbox{ Hz } \mbox \mbox{ Hz } Hz $	$\begin{array}{c c c c c c c c c c c c c c c c c c c $

Measurement mode	Selectable between RMS of			
Measurement items	Current integration (Ih+, Ih-, Ih+ and Ih- only for DC mod measurements	and Ih), active po de measurements	ower integration (W s, and Ih only for R	P+, WP-, and WP MS mode
Measurement method	Digital calculation from each		e power phase (whe	n averaging,
	calculates with previous aver In DC mode: calculates cur		rv sample and inte	arates
	instantaneous power indep			grates
	In RMS mode: Integrates curre		between measurem	ent intervals, and
Measurement interval	polarity-independent active po 50 ms data update interval	ower value		
Measuring range	Integration value: 0 Ah/Wh	to +9999.99 TAh	/TWh	
	Integration time: No greater	r than 9999h59m		
Integration time accuracy	±50 ppm ±1 dgt. (0°C to 40			
Integration accuracy	± (current and active power			асу
Backup function	Integration automatically re	sumes after pow	er outages.	
4. Harmonic Meas	urement Specification	าร		
Number of	4 channels			
measurement channels				
Measurement items	Harmonic rms voltage, harmo harmonic rms current, harmo			
	harmonic active power, harm			
	difference, total harmonic vol	tage distortion, tot	al harmonic current	
Measurement method	voltage unbalance factor, cur			window) with gon
measurement method	Zero-crossing synchronous Fixed 500 kS/s sampling, a			with gap
	Equal thinning between zer			ulation)
Harmonic sync source	U1 to U4, I1 to I4, External		sis and CH B set for	or pulse input), DC
FFT calculation word	selectable (50 ms or 100 m 32 bits	IS)		
length	52 0115			
Anti-aliasing filter	Digital filter (automatically s	set based on syn	chronization freque	ency)
Windows	Rectangular			
Synchronization	As specified for power mea	surements		
frequency range	50 ma (maaauramant fragu	anov denordant	at 45 Hz and halo	
Data update interval Phase zero adjustment	50 ms (measurement-freque Provided by key operation or e			
THD calculation	THD-F/THD-R		innana (oni) introve	
Highest order analysis	Synchronization	Window	Analysis order	٦
and window waveforms	frequency range	waveforms	Analysis order	
	0.5 Hz ≤ f < 40 Hz	1	100th	1
	40 Hz ≤ f < 80 Hz	1	100th	
	80 Hz ≤ f < 160 Hz	2	80th	
	160 Hz ≤ f < 320 Hz	4	40th	_
	320 Hz ≤ f < 640 Hz	8	20th	
	640 Hz ≤ f < 1.2 kHz	16	10th	
		16 32	10th 5th	_
	640 Hz ≤ f < 1.2 kHz			_
Accuracy	640 Hz ≤ f < 1.2 kHz 1.2 kHz ≤ f < 2.5 kHz 2.5 kHz ≤ f < 5.0 kHz	32 64	5th 3th	wer(P)
Accuracy	640 Hz ≤ f < 1.2 kHz 1.2 kHz ≤ f < 2.5 kHz	32 64 Voltage(U), C	5th 3th urrent(I), Active Po	wer(P)
Accuracy	640 Hz ≤ f < 1.2 kHz 1.2 kHz ≤ f < 2.5 kHz 2.5 kHz ≤ f < 5.0 kHz Frequency	32 64	5th 3th urrent(I), Active Po 0.2% f.s.	wer(P)
Accuracy	$640 \text{ Hz} \le f < 1.2 \text{ kHz}$ $1.2 \text{ kHz} \le f < 2.5 \text{ kHz}$ $2.5 \text{ kHz} \le f < 5.0 \text{ kHz}$ Frequency $0.5 \text{ Hz} \le f < 30 \text{ Hz}$	32 64 Voltage(U), C ±0.4% rdg. ±0	5th 3th urrent(I), Active Po 0.2% f.s. 0.1% f.s.	wer(P)
Accuracy	$\begin{array}{l} 640 \mbox{ Hz } \le f < 1.2 \mbox{ kHz } \\ 1.2 \mbox{ kHz } \le f < 2.5 \mbox{ kHz } \\ 2.5 \mbox{ kHz } \le f < 5.0 \mbox{ kHz } \\ \hline \end{tabular}$	32 64 Voltage(U), C ±0.4% rdg. ±0 ±0.3% rdg. ±0	5th 3th urrent(I), Active Po .2% f.s. 0.1% f.s. 0.2% f.s.	wer(P)
Accuracy	$\begin{array}{l} 640 \text{ Hz} \le 1 < 1.2 \text{ kHz} \\ 1.2 \text{ kHz} \le 1 < 2.5 \text{ kHz} \\ 2.5 \text{ kHz} \le 1 < 5.0 \text{ kHz} \\ \hline \\ $	32 64 Voltage(U), C ±0.4% rdg. ±0 ±0.3% rdg. ±0 ±0.4% rdg. ±0	5th 3th 0.2% f.s. 0.1% f.s. 0.2% f.s. 0.1% f.s. 0.2% f.s. 0.2% f.s. 0.5% f.s.	wer(P)
Accuracy	640 Hz ≤ f < 1.2 kHz 1.2 kHz ≤ f < 2.5 kHz 2.5 kHz ≤ f < 5.0 kHz Frequency 0.5 Hz ≤ f < 30 Hz 30 Hz ≤ f < 400 Hz 400 Hz < f ≤ 1 kHz 1 kHz < f ≤ 5 kHz	32 64 Voltage(U), C ±0.4% rdg. ±0 ±0.3% rdg. ±0 ±0.4% rdg. ±0 ±1.0% rdg. ±0	5th 3th 0.2% f.s. 1.1% f.s. 1.2% f.s. 1.2% f.s. 1.5% f.s. 0.0% f.s.	wer(P)
Accuracy	$\begin{array}{l} 640 \mbox{ Hz } \le 1 < 1.2 \mbox{ kHz } \\ 1.2 \mbox{ kHz } \le 1 < 2.5 \mbox{ kHz } \\ 2.5 \mbox{ kHz } \le 1 < 5.0 \mbox{ kHz } \\ \hline \end{tabular}$	32 64 Voltage(U), C ±0.4% rdg.±0 ±0.4% rdg.±0 ±1.0% rdg.±0 ±2.0% rdg.±1 ±5.0% rdg.±1	Sth 3th urrent(I), Active Po 0.2% f.s. 1.1% f.s. 2.2% f.s. .5% f.s. .0% f.s.	wer(P)
	640 Hz ≤ f < 1.2 kHz 1.2 kHz ≤ f < 2.5 kHz 2.5 kHz ≤ f < 2.5 kHz Frequency 0.5 Hz ≤ f < 30 Hz 30 Hz ≤ f < 30 Hz 400 Hz < f ≤ 1 kHz 1 kHz < f ≤ 5 kHz 5 kHz < f ≤ 10 kHz 10 kHz < f ≤ 13 kHz	32 64 Voltage(U), C ±0.4% rdg.±0 ±0.4% rdg.±0 ±1.0% rdg.±0 ±2.0% rdg.±1 ±5.0% rdg.±1	Sth 3th urrent(I), Active Po 0.2% f.s. 1.1% f.s. 2.2% f.s. .5% f.s. .0% f.s.	wer(P)
5. Noise Measurer	$\begin{array}{l} 640 \ \text{Hz} \le 1 < 1.2 \ \text{kHz} \\ 1.2 \ \text{kHz} \le 1 < 2.5 \ \text{kHz} \\ 2.5 \ \text{kHz} \le 1 < 5.0 \ \text{kHz} \\ \hline \\ $	32 64 Voltage(U), C ±0.4% rdg.±0 ±0.3% rdg.±0 ±1.0% rdg.±0 ±1.0% rdg.±1 ±2.0% rdg.±1 ±5.0% rdg.±1	Sth 3th urrent(I), Active Po 0.2% f.s. 1.1% f.s. 2.2% f.s. .5% f.s. .0% f.s.	wer(P)
5. Noise Measurer Calculation channels Calculation items	$\begin{array}{l} 640 \ \text{Hz} \le 1 < 1.2 \ \text{kHz} \\ 1.2 \ \text{kHz} \le 1 < 2.5 \ \text{kHz} \\ 1.2 \ \text{kHz} \le 1 < 2.5 \ \text{kHz} \\ 2.5 \ \text{kHz} \le 1 < 5.0 \ \text{kHz} \\ \hline \end{array}$	32 64 Voltage(U), C ±0.4% rdg.±C ±0.4% rdg.±C ±1.0% rdg.±0 ±2.0% rdg.±1 ±5.0% rdg.±1 ±5.0% rdg.±1 tencies of 4.3 kH e above when us	Sth 3th urrent(I), Active Po 0.2% f.s. 1.1% f.s. 2.2% f.s. .5% f.s. .0% f.s.	wwer(P)
5. Noise Measurer Calculation channels Calculation items Calculation type	$\begin{array}{l} 640 \mbox{ Hz } \le 1 < 1.2 \mbox{ kHz } \\ 1.2 \mbox{ kHz } \le 1 < 2.5 \mbox{ kHz } \\ 1.2 \mbox{ kHz } \le 1 < 5.0 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 < 5.0 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 < 5.0 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 < 3.0 \mbox{ Hz } \\ \hline 1.2 \mbox{ kHz } \le 1 \le 0.0 \mbox{ Hz } \\ \hline 1.2 \mbox{ kHz } \le 1 \le 0.0 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 \le 0.0 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 \le 0.0 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 \le 0.0 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \mbox{ kHz } \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \mbox{ kHz } \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \mbox{ kHz } \mbox{ kHz } \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \$	32 64 Voltage(U), C ±0.4% rdg.±0 ±0.4% rdg.±0 ±1.0% rdg.±0 ±1.0% rdg.±1 ±5.0% rdg.±1 ±5.0% rdg.±1 encies of 4.3 kH e above when us	Sth 5th 3th	wwer(P)
5. Noise Measurer Calculation channels Calculation items Calculation type Calculation method	$\begin{array}{l} 640 \mbox{ Hz } \le 1 < 1.2 \mbox{ kHz } \\ 1.2 \mbox{ kHz } \le 1 < 2.5 \mbox{ kHz } \\ 1.2 \mbox{ kHz } \le 1 < 2.5 \mbox{ kHz } \\ 1.2 \mbox{ kHz } \le 1 < 5.0 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 < 5.0 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 < 5.0 \mbox{ kHz } \\ 1.2 \mbox{ kHz } \le 1 \mbox{ kHz } \\ 1.2 \mbox{ kHz } \le 1 \mbox{ kHz } \\ 1.2 \mbox{ kHz } \le 1 \mbox{ kHz } \\ 1.2 \mbox{ kHz } \le 1 \mbox{ kHz } \\ 1.2 \mbox{ kHz } \le 1 \mbox{ kHz } \\ 1.2 \mbox{ kHz } \le 1 \mbox{ kHz } \\ 1.2 \mbox{ kHz } \mbox{ kHz } \\ 1.2 \mbox{ kHz }$	32 64 Voltage(U), C ±0.4% rdg.±0 ±0.4% rdg.±0 ±1.0% rdg.±0 ±1.0% rdg.±1 ±5.0% rdg.±1 ±5.0% rdg.±1 encies of 4.3 kH e above when us	Sth 5th 3th	wer(P)
5. Noise Measurer Calculation channels Calculation items Calculation type Calculation method FFT calculation word	$\begin{array}{l} 640 \mbox{ Hz } \le 1 < 1.2 \mbox{ kHz } \\ 1.2 \mbox{ kHz } \le 1 < 2.5 \mbox{ kHz } \\ 1.2 \mbox{ kHz } \le 1 < 5.0 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 < 5.0 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 < 5.0 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 < 3.0 \mbox{ Hz } \\ \hline 1.2 \mbox{ kHz } \le 1 \le 0.0 \mbox{ Hz } \\ \hline 1.2 \mbox{ kHz } \le 1 \le 0.0 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 \le 0.0 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 \le 0.0 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 \le 0.0 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \mbox{ kHz } \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \mbox{ kHz } \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \mbox{ kHz } \mbox{ kHz } \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } kHz $	32 64 Voltage(U), C ±0.4% rdg.±0 ±0.4% rdg.±0 ±1.0% rdg.±0 ±1.0% rdg.±1 ±5.0% rdg.±1 ±5.0% rdg.±1 encies of 4.3 kH e above when us	Sth 5th 3th	wer(P)
5. Noise Measurer Calculation channels Calculation items Calculation type Calculation method FFT calculation word length FFT data points	$\begin{array}{l} 640 \mbox{ Hz } \le 1 < 1.2 \mbox{ kHz } \\ 1.2 \mbox{ kHz } \le 1 < 2.5 \mbox{ kHz } \\ 1.2 \mbox{ kHz } \le 1 < 2.5 \mbox{ kHz } \\ 1.2 \mbox{ kHz } \le 1 < 5.0 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 < 5.0 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 < 5.0 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \mbox{ kHz } \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \mbox{ kHz } \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \mbox{ kHz } \mbox{ kHz } \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \$	32 64 Voltage(U), C ±0.4% rdg.±0 ±0.4% rdg.±0 ±1.0% rdg.±0 ±1.0% rdg.±1 ±5.0% rdg.±1 ±5.0% rdg.±1 uencies of 4.3 kH e above when us CH4) e (according to disp	5th 5th 3th urrent(I), Active Po 1.2% f.s. 1.2% f.s. 5% f.s. 0.0% f.s. 0.0% f.s. 2 and higher ing LPF.	ecording length)
5. Noise Measurer	$\begin{array}{l} 640 \mbox{ Hz } \le 1 < 1.2 \mbox{ kHz } \\ 1.2 \mbox{ kHz } \le 1 < 2.5 \mbox{ kHz } \\ 1.2 \mbox{ kHz } \le 1 < 5.0 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 < 5.0 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 < 5.0 \mbox{ kHz } \\ \hline 1.2 \mbox{ kHz } \le 1 < 3.0 \mbox{ Hz } \\ \hline 3.0 \mbox{ Hz } \le 1 \le 400 \mbox{ Hz } \\ \hline 3.0 \mbox{ Hz } \le 1 \le 400 \mbox{ Hz } \\ \hline 3.0 \mbox{ Hz } \le 1 \le 400 \mbox{ Hz } \\ \hline 3.0 \mbox{ Hz } \le 1 \le 10 \mbox{ kHz } \\ \hline 3.0 \mbox{ Hz } \le 1 \le 10 \mbox{ kHz } \\ \hline 3.0 \mbox{ kHz } \le 1 \le 10 \mbox{ kHz } \\ \hline 3.0 \mbox{ kHz } \le 1 \mbox{ kHz } \\ \hline 3.0 \mbox{ kHz } \le 1 \mbox{ kHz } \\ \hline 3.0 \mbox{ kHz } \le 1 \mbox{ kHz } \\ \hline 3.0 \mbox{ kHz } \mbox{ kHz } \\ \hline 3.0 \mbox{ kHz } \mbox{ kHz } \\ \hline 3.0 \mbox{ kHz } \\ \hline 3.$	32 64 Voltage(U), C ±0.4% rdg.±C ±0.4% rdg.±C ±1.0% rdg.±0 ±2.0% rdg.±1 ±5.0% rdg.±1 ±5.0% rdg.±1 (according to 4.3 kH e above when us CH4) e (according to disp as with maximum	5th 5th 3th urrent(I), Active Po 1.2% f.s. 1.2% f.s. 5% f.s. 0.0% f.s. 0.0% f.s. 2 and higher ing LPF.	ecording length)

 Data update interval
 Determined by FFT points within approx. 400 ms, 1 s, 2 s, or 15 s, with gap

 Highest analysis frequency
 100 kHz/50 kHz/20 kHz/10 kHz/5 kHz/2 kHz

 Frequency resolution
 0.2 Hz to 500 Hz (Determined by FFT points and maximum analysis frequency)

 Noise amplitude measurement Lower limit noise frequency
 Calculates the ten highest level and frequency voltage and current FFT peak values (local maxima).

 Lower limit noise frequency
 0 kHz to 10 kHz

-6. Motor Analysis Specifications (Model PW3390-03)

Number of input channels	3 channels CH A: Analog DC input/Frequency input (selectable) CH B: Analog DC input/Pulse input (selectable) CH Z: Pulse input
Measurement input terminal type	Insulated BNC jacks
Input impedance (DC)	1 MΩ ±100 kΩ
Input methods	Isolated and differential inputs (not isolated between channels B and Z)
Measurement items	Voltage, torque, rotation rate, frequency, slip, and motor power
Synchronization source	U1 to U4, I1 to I4, Ext (with CH B set for pulse input), DC (50 ms/100 ms) Common to channels A and B
Measurement frequency source	f1 to f4 (for slip calculations)
Maximum input voltage	±20 V (during analog, frequency, and pulse input)
Maximum rated voltage to earth	50 V (50 Hz/60 Hz)
(1). Analog DC Inpu	ut (CH A/CH B)
Measurement range	±1 V, ±5 V, ±10 V (when inputting analog DC)
Valid input range	1% to 110% f.s.
Sampling	10 kHz/16 bits
Response time	1 ms (measuring zero to full scale, with LPF off)
Measurement method	Simultaneous digital sampling and zero-crossing synchronous calculation system (cumulative average of intervals between zero crossings)
	(culturative average of intervals between zero crossings)

Temperature coefficient	±0.03% f.s./°C
Effect of common mode voltage	Not more than ±0.01% f.s. (with 50 V [DC or 50 Hz/60 Hz] between measurement jacks and PW3390
Effect of external	chassis) Not more than ±0.1% f.s. (at 400 A/m DC and 50 Hz/60 Hz magnetic fields)
magnetic field LPF	OFF/ON (OFF: 4 kHz, ON: 1 kHz)
Total display area	Zero-suppression range setting ±120%
Zero adjustment	Zero-corrected input offset of voltage ±10% f.s. or less
Scaling	0.01 ~ 9999.99
Unit	CH A: V, N• m, mN• m, kN• m CH B: V, Hz, r/min
2). Frequency Inpu	ut (CH A only)
Valid amplitude range Max. measurement	±5 V peak (5 V symmetrical, equivalent to RS-422 complementary signal) 100 kHz
frequency Moscurement range	1 kHz to 100 kHz
Measurement range Data output interval	According to synchronization source
Measurement accuracy	
Total display area	1.000 kHz to 99.999 kHz
Frequency range	Select fc and fd for frequency range fc \pm fd [Hz] (frequency measurement only 1 kHz to 98 kHz in 1 kHz units, where fc + fd < 100 kHz and fc - fd > 1 kHz
Rated torque	1 ~ 999
Unit	Hz, N• m, mN• m, kN• m
3). Pulse Input (CH	
Detection level	Low: 0.5 V or less; High: 2.0 V or more
Measurement range Division setting range	1 Hz to 200 kHz (at 50% duty) 1 ~ 60000
Division setting range Measurement	 0.5 Hz to 5.0 kHz (limited to measured pulse frequency divided by selected not
frequency range Minimum detectable	$2.5 \mu s$ or more
pulse width	2.5 µ3 01 11010
Measurement accuracy	
Motor poles Max. measurement	2 ~ 98 100 Hz, 500 Hz, 1 kHz, 5 kHz
frequency	
Pulse count	Integer multiple of half the number of motor poles, from 1 to 60,000
Unit	Hz, r/min
4). Pulse Input (CH	
Detection level Measurement range	Low: 0.5 V or less; High: 2.0 V or more 0.1 Hz to 200 kHz (at 50% duty)
Minimum detectable	2.5 µs or more
pulse width	OEE/Z Bhase/R Bhase (clear counts of CHR in riging odge during Z Bhase
Settings	OFF/Z Phase/B Phase (clear counts of CHB in rising edge during Z Phase, detect polar code for number of rotations during B Phase)
7. D/A Output Opti	on Specifications (Models PW3390-02 and PW3390-03)
Number of output	16 channels
channels Output contents	CH1 to CH8: Selectable analog/waveform outputs
	CH9 to CH16: Analog output
Output items	Analog output: Select a basic measurement item for each output channel. Waveform output: Output voltage or current measured waveforms.
Output connector	One 25-pin female D-sub
D/A conversion resolution	16 bits (polarity + 15 bits)
Output accuracy	Analog output: Measurement accuracy ±0.2% f.s. (DC level)
	Waveform output: Measurement accuracy ±0.5% f.s. (at ±2 V f.s.), ±1.0% f.s. (at ±1 V f.s.)
	(rms level within synchronous frequency range)
Output update interval	Analog output: 50 ms (according to input data update interval of selected parameter Waveform output: 500 kHz
Output voltage	Analog output: ±5 V DC nom. (approx. ±12 V DC max.) Waveform output: ±2 V/±1 V switchable, crest factor of 2.5 or greater
Output impedance	Setting applies to all channels. 100 Ω ±5 Ω
Temperature coefficient	±0.05% f.s./°C
·8. Display Specific	Leations
Display type	9-inch TFT color LCD (800×480 dots)
Display refresh interval	Measurement values: 200 ms (independent of internal data update interval)
	Waveforms, FFT: screen-dependent
9. External Interface (
Connector	Mini-B receptacle ×1
Compliance standard	USB2.0 (Full Speed/High Speed)
Class	Individual (USB488h)
Connection destination Function	Computer (Windows10/Windows8/Windows7, 32bit/64bit) Data transfer and command control
2). USB Memory Ir	
Connector	USB type A connector ×1
Compliance standard	USB2.0
USB power supply	500 mA maximum
USB storage device support	USB Mass Storage Class
Function	Save and load settings files, Save waveform data
	Save displayed measurement values (CSV format) Copy measurement values and recorded data (from CF card)
	Save screen captures
3). LAN Interface	
	RJ-45 connector x 1
(3). LAN Interface Connector Compliance standard	IEEE 802.3 compliant
Connector Compliance standard Transmission method	IEEE 802.3 compliant 10BASE-T/100BASE-TX Auto detected
Connector Compliance standard	IEEE 802.3 compliant

Slot	One Type 1
Compatible card	CompactFlash memory card (32 MB or higher)
Supported memory capacity	Up to 2 GB
Data format	MS-DOS format (FAT16/FAT32)
Recordable content	Save and load settings files, Save waveform data Save displayed measurement values and auto-recorded data (CSV format, Copy measurements/recorded data (from USB storage) Save screen captures
(5). RS-232C Interf	ace
Method	RS-232C, [EIA RS-232D], [CCITT V.24], [JIS X5101] compliant Full duplex, start-stop synchronization, 8-bit data, no parity, one stop bit Hardware flow control, CR+LF delimiter
Connector	D-sub9 pin connector ×1
Communication speeds	9600 bps, 19,200 bps, 38,400 bps
Function	Command control, Bluetooth® logger connectivity (simultaneous use not supported)
(6). Synchronization	n Control Interface
Signal contents	One-second clock, integration START/STOP, DATA RESET, EVENT
Connector types	IN: One 9-pin female mini-DIN jack, OUT: One 8-pin female mini-DIN jack
Signal	5 V CMOS
Max. input	±20 V
Max. signal delay	2 μs (rising edge)
(7). External Contro	bl Interface
Connector types	9-pin round connector x1; also used as synchronization control interface
Electrical specifications	Logic signal of 0 V/5 V (2.5 V to 5 V), or contact signal (shorted/open)
Function	Integration start integration stop, data reset, event (the event set as the

Signal	5 V CMOS
Max. input	±20 V
Max. signal delay	2 µs (rising edge)
(7). External Contro	ol Interface
Connector types	9-pin round connector ×1; also used as synchronization control interface
Electrical specifications	Logic signal of 0 V/5 V (2.5 V to 5 V), or contact signal (shorted/open)
Function	Integration start, integration stop, data reset, event (the event set as the synchronization control function) Cannot be used at the same time as synchronization control.

Function Specifications

AUTO range function	Automatically selects voltage and current ranges according to measured ampli-
Ao to tange function	tude on each phase.
	Operating states: Selectable on or off for each phase system
	Auto-ranging span: Wide/Narrow (common to all wiring systems)
Timing control function	Interval OFF/50 ms/100 ms/200 ms/500 ms/1 s/5 s/10 s/
	15 s/30 s/1 min/5 min/10 min/15 min/30 min/60 min
	Setting determines the maximum data-saving capacity
	Timing controls OFF/Timer/BTC
	Timer : 10 s to 9999:59:59 [h:m:s] (in seconds)
	Real-time clock : Start and stop times (in minutes)
Hold function	Stops all updating of displayed measurement values and waveforms, and holds
	display.
	Internal calculations such as integration and averaging, clock, and peak-over display continue to be updated.
Peak hold function	All measurement values are updated to display the maximum value for each
	measurement.
	Displayed waveforms and integration values continue to be updated with instan- taneous values.
2. Calculation Fun	ctions
Scaling calculation	VT(PT) ratio and CT ratio: OFF/0.01 to 9999.99
Average calculation	OFF/FAST/MID/SLOW/SLOW2/SLOW3
	Exponentially averages all instantaneous measurement values including
	harmonics (but not peak, integration, or FFT noise values). Applied to displayed values and saved data.
	Response speed (time remains within specified accuracy when input changes
	from 0 to 100% f.s.)
	FAST: 0.2 s, MID: 1.0 s, SLOW: 5 s, SLOW2: 25 s, SLOW3: 100 s
Efficiency and loss	Efficiency η [%] and Loss [W] are calculated from active power values measured
calculations	on each phase and system. For PW3390-03, motor power (Pm) is also applied as a calculation item.
	Maximum no. of simultaneous calculations: Efficiency and loss, by three
	formulas (Parameters are specified for Pin and Pout)
	Calculation method: Efficiency η = 100 × IPoutI/IPinI Loss = IPinI - IPoutI
∆-Y calculation	For 3P3W3M systems, converts between line-to-line voltage and phase voltage
	waveforms using a virtual center point.
	All voltage parameters including harmonics such as true rms voltage are calculated as
	phase voltage waveforms. U1s = (U1s-U3s)/3, U2s = (U2s-U1s)/3, U3s =(U3s-U2s)/3
Selecting the	TYPE1/TYPE2 (only valid when wiring is 3P3W3M)
calculation method	Select the calculation method used to calculate the apparent power and reactive
	power during 3P3W3M wiring.
Current sensor phase	Only affect measurement values S123, Q123, φ123, λ123
correction calculations	Compensation by calculating the current sensor's harmonic phase characteristics Correction points are set using frequency and phase difference (set separately
	for each wiring mode).
	Frequency: 0.001 kHz to 999.999 kHz (in 0.001 kHz increments)
	Phase difference: 0.00 deg. to ±90.00 deg. (in 0.01 deg. increments) However, the time difference calculated from the frequency phase difference is
	limited to a maximum of 200 us in 5 ns increments.
3. Display Functio	ns
Wiring Check screen	The wiring diagram and voltage/current vectors are displayed for the selected
	wiring system(s).
	The correct range for the wiring system is shown on the vector display, to confirm proper measurement cable connections.
Independent wiring	Displays power and harmonic measurement values for channels 1 to 4.
system display mode	A composite measurement line pattern is displayed for each system.
	Basic, voltage, current, and power measurement parameter,
Display Calastian	harmonic bar graph, harmonic list, and harmonic vector screens
Display Selections screen	Select to display any 4, 8, 16, or 32 of the basic measurement parameters. Display layout: 4, 8, 16, or 32 parameters (4 patterns)
Efficiency and Loss screen	The efficiency and loss obtained by the specified calculation formulas are displayed numerically. Three efficiency and three loss values.

Waveform & Noise screen	Voltage and current waveforms sampled at 500 kHz and noise measurements are displayed compressed on one screen. Trigger: Synchronized with the harmonic sync source Recording length: 1000/5000/10,000/50,000 x All voltage and current channels Compression ratio: 1/1, 1/2, 1/5, 1/10, 1/20, 1/50 (peak-to-peak compression) Recording time:				
	Recording speed/ Recording length	1000	5000	10,000	50,000
	500 kS/s	2 ms	10 ms	20 ms	100 ms
	250 kS/s 100 kS/s	4 ms 10 ms	20 ms 50 ms	40 ms 100 ms	200 ms 500 ms
	50 kS/s	20 ms	100 ms	200 ms	1000 ms
	25 kS/s	40 ms	200 ms	400 ms	2000 ms
	10 kS/s	100 ms	500 ms	1000 ms	5000 ms
X-Y Plot screen	Select horizontal and vertical axes from the basic measurement items to displa on the X-Y graphs. Dots are plotted at the data update interval, and are not saved. Drawing data can be cleared. Horizontal: 1 data item (gauge display available), Vertical: 2 data items (gauge display available)				
-4. Saving Function					
Auto-save function	As the items to be saw noise value data of the during every measure Can be controlled by t Max. no. of saved item Data format: CSV form	e FFT function ment interval. imer or real-tir ns: Interval-set	. The selected (Storage to U ne clock.	d items are sto SB memory is	ored to CF ca
Manual saving function			card		
	Measurement data As the items to be and noise value da Pressing the SAVI the save destination File format: CSV fc Screen capture The COPY key can destination. "This function can saving is in progre File format: Comp Settings data Settings data Settings data Settings data Saves the wavefor File format: CSV fc	ta of the FFT E key saves ea on. ormat botures and sav be used at an ss. ressed BMP fc on can be save ormat (for PW3 m being displa	function. Ich measuren res a bitmap in interval of 5 s prmat ed/loaded as a 3390 only)	nent value at th mage of the di sec or more wi a settings file.	hat moment to splay to the s
-5. Synchronous C		Jinat			
Function	Synchronous measure Model PW3390 (mast When internal settings	er/slave).			
Synchronized items	Clock, data update int	erval (except f			
Event items	data reset, certain events Hold, manual save, screen capture				
Synchronization timing	 Clock, data update ir Within 10 s after p Start/stop, data rese 	nterval ower-on by a s	ave PW3390	I	
Synchronization delay	Upon key-press ar Maximum 5 µs per con				
-6. Bluetooth [®] Log		lection. Maxim	un synchioniz	alloir delay or a	
Function	Sends measured valu	es wirelessly t	o logger by us	ing a Bluetoo	th® serial
		conversion adapter.			
Supported devices	Hioki LR8410 Link-compatible loggers (LR8410, LR8416) Measured values assigned to the D/A CH9 to CH16 analog output parameters				
					out parameter
Supported devices	Measured values assi				out parameter
Supported devices Sent data -7. Other Functions Display language selection	Measured values assi	gned to the D/			out parameter
Supported devices Sent data -7. Other Functions Display language selection Beep sound	Measured values assi Japanese, English, Cl OFF/ON	gned to the D/ ninese	A CH9 to CH1	6 analog outp	out parameter
Supported devices Sent data -7. Other Functions Display language selection	Measured values assi	gned to the D/ ninese ue-green)/3 (b	A CH9 to CH1	6 analog outp	out parameter
Supported devices Sent data -7. Other Functions Display language selection Beep sound Screen color schemes Start-up screen selection LCD backlight	Measured values assi Japanese, English, Cł OFF/ON COLOR1 (black)/2 (bli Wiring or Last-display ON/1 min/5 min/10 mi	gned to the D/ ninese ue-green)/3 (b ed screen (Me	A CH9 to CH1 lue)/4 (gray)/5	6 analog outp	ut parameter
Supported devices Sent data 7. Other Functions Display language selection Beep sound Screen color schemes Start-up screen selection LCD backlight CSV file format	Measured values assi Japanese, English, Cl OFF/ON COLOR1 (black)/2 (bl Wiring or Last-display ON/1 min/5 min/10 mi CSV/SSV	gned to the D/ ninese ue-green)/3 (b ed screen (Me n/30 min/60 m	A CH9 to CH1 lue)/4 (gray)/5 asurement so	6 analog outp	ut parameter
Supported devices Sent data -7. Other Functions Display language selection Beep sound Screen color schemes Start-up screen selection LCD backlight CSV file format Beal-time clock function	Measured values assi Japanese, English, Cl OFF/ON COLOR1 (black)/2 (bl Wiring or Last-display ON/1 min/5 min/10 mi CSV/SSV Auto-calendar, leap-y	gned to the D/ ninese ue-green)/3 (b ed screen (Me n/30 min/60 m ear correcting	A CH9 to CH1 lue)/4 (gray)/5 asurement so	6 analog outp	ut parameter
Supported devices Sent data 7. Other Functions Display language selection Beep sound Screen color schemes Start-up screen selection LCD backlight CSV file format	Measured values assi Japanese, English, Cl OFF/ON COLOR1 (black)/2 (bl Wiring or Last-display ON/1 min/5 min/10 mi CSV/SSV Auto-calendar, leap-y ±3 s per day @25°C (Current sensors are a	gned to the D/ ninese ue-green)/3 (b ed screen (Me n/30 min/60 m ear correcting 77°F) utomatically re	A CH9 to CH1 lue)/4 (gray)/5 rasurement so in 24-hour clock	6 analog outp i (navy blue) reens only)	
Supported devices Sent data -7. Other Functions Display language selection Beep sound Screen color schemes Start-up screen selection LCD backlight CSV file format Real-time clock function RTC accuracy	Measured values assi Japanese, English, Cl OFF/ON COLOR1 (black)/2 (bl Wiring or Last-display ON/1 min/5 min/10 mi CSV/SSV Auto-calendar, leap-yi ±3 s per day @25°C (Current sensors are a CT7000 series sensor When peak over occu no sync source is dete	gned to the D/ hinese ue-green)/3 (b ed screen (Me n/30 min/60 m ear correcting 77°F) utomatically re s) rs on voltage a coted	A CH9 to CH1 lue)/4 (gray)/5 assurement so in 24-hour clock accognized who and current m	6 analog out; (navy blue) reens only) an connected pasurement cl	(Excluding th
Supported devices Sent data -7. Other Functions Display language selection Beep sound Screen color schemes Start-up screen selection LCD backlight CSV file format Real-time clock function RTC accuracy Sensor recognition Warning indicators Key-lock	Measured values assi Japanese, English, Cl OFF/ON COLOR1 (black)/2 (bl Wiring or Last-display ON/1 min/5 min/10 mi CSV/SSV Auto-calendar, leap-yr ±3 s per day @25°C (Current sensors are a CT7000 series sensor When peak over occu no sync source is dete Warning indicators for Toggles on/off by hold	gned to the D/ hinese ue-green)/3 (b ed screen (Me n/30 min/60 m ear correcting 77°F) utomatically re 's) rs on voltage a cted all channels ai ing the ESC k	A CH9 to CH1 lue)/4 (gray)/5 assurement sc in 24-hour clock and current m re displayed o ey for three sc	6 analog outp (navy blue) (reens only) en connected assurement ct n all pages of t	(Excluding th
Supported devices Sent data -7. Other Functions Display language selection Beep sound Screen color schemes Start-up screen selection LCD backlight CSV file format Real-time clock function RTC accuracy Sensor recognition Warning indicators	Measured values assi Japanese, English, Cl OFF/ON COLOR1 (black)/2 (bl Wiring or Last-display ON/1 min/5 min/10 mi CSV/SSV Auto-calendar, leap-yr ±3 s per day @25°C (Current sensors are a CT7000 series sensor When peak over occu no sync source is dete Warning indicators for	gned to the D/ hinese ue-green)/3 (b ed screen (Me n/30 min/60 m ear correcting 77°F) uutomatically re s) rs on voltage a beted all channels al ing the ESC k factory defaul	A CH9 to CH1 lue)/4 (gray)/5 assurement so in 24-hour clock ecognized wh and current m re displayed o y for three so ts	6 analog out; (navy blue) (navy blue) (na	(Excluding th hannels, Whe

General Specifications

Operating environment Indoors, Pollution Degree 2, altitude up to 2000 m (6562.20 ft) Operating temperature Temperature: 0° to 40°C (32°F to 104°F), Humidity: 80% RH or less and humidity (no condensation) Storage temperature and humidity -10°C to 50°C (14°F to 122°F), 80% RH or less (no condensation) Dustproof and waterproof IP30 (EN 60529) (With CF card cover open: IP20) Applicable standards Safety EN 61010 EMC Power supply 100 V to 240 V AC, 50 Hz/60 Hz, Maximum rated power: 140 VA Anticipated transient overvoltage: 2500 V Backup battery life Clock, settings and integration values (Lithium battery), Approx. 10 years, @23°C (73°F) Dimensions 340 mm (13.39 in) W × 170 mm (6.69 in) H × 156 mm (6.14 in) D (excluding protrusions) Mass 4.6 kg (162.3 oz) with PW3390-03 Product warranty period 1 year Accessories Instruction Manual ×1, Measurement Guide ×1, Power cord ×1, USB cable (0.9 m (2.95 tt)) ×1, Input cord label ×2, D-sub connector ×1 (PW3390-02, PW3390-03)			
and humidity (no condensation) Storage temperature and humidity -10°C to 50°C (14°F to 122°F), 80% RH or less (no condensation) Dustproof and waterproof IP30 (EN 60529) (With CF card cover open: IP20) Applicable standards Safety EN 61326 Class A Power supply 100 V to 240 V AC, 50 Hz/60 Hz, Maximum rated power: 140 VA Anticipated transient overvoltage: 2500 V Backup battery life Clock, settings and integration values (Lithum battery), Approx. 10 years, @23°C (73°F) Dimensions 340 mm (13.39 in) W × 170 mm (6.69 in) H × 156 mm (6.14 in) D (excluding protrusions) Mass 4.6 kg (162.3 oz) with PW3390-03 Product warranty period 1 year Instruction Manual ×1, Measurement Guide ×1, Power cord ×1, USB cable (0.9 m	Operating environment	Indoors, Pollution Degree 2, altitude up to 2000 m (6562.20 ft)	
and humidity Image: Constraint of the second s			
Applicable standards Safety EN 61010 EMC EN 61326 Class A Power supply 100 V to 240 V AC, 50 Hz/60 Hz, Maximum rated power: 140 VA Anticipated transient overvoltage: 2500 V Backup battery life Clock, settings and integration values (Lithium battery), Approx. 10 years, @23°C (73°F) Dimensions 340 mm (13.39 in) W × 170 mm (6.69 in) H × 156 mm (6.14 in) D (excluding protrusions) Mass 4.6 kg (162.3 oz) with PW3390-03 Product warranty period 1 year Instruction Manual ×1, Measurement Guide ×1, Power cord ×1, USB cable (0.9 m		-10°C to 50°C (14°F to 122°F), 80% RH or less (no condensation)	
EMC EN 61326 Class A Power supply 100 V to 240 V AC, 50 Hz/60 Hz, Maximum rated power: 140 VA Anticipated transient overvoltage: 2500 V Backup battery life Clock, settings and integration values (Lithium battery), Approx. 10 years, @23°C (73°F) Dimensions 340 mm (13.39 in) W × 170 mm (6.69 in) H × 156 mm (6.14 in) D (excluding protrusions) Mass 4.6 kg (162.3 oz) with PW3390-03 Product warranty period 1 year Accessories Instruction Manual ×1, Measurement Guide ×1, Power cord ×1, USB cable (0.9 m	Dustproof and waterproof	IP30 (EN 60529) (With CF card cover open: IP20)	
Anticipated transient overvoltage: 2500 V Backup battery life Clock, settings and integration values (Lithium battery), Approx. 10 years, @23°C (73°F) Dimensions 340 mm (13.39 in) W × 170 mm (6.69 in) H × 156 mm (6.14 in) D (excluding protrusions) Mass 4.6 kg (162.3 oz) with PW3390-03 Product warranty period 1 year Accessories Instruction Manual ×1, Measurement Guide ×1, Power cord ×1, USB cable (0.9 m	Applicable standards		
Dimensions 340 mm (13.39 in) W × 170 mm (6.69 in) H × 156 mm (6.14 in) D (excluding protrusions) Mass 4.6 kg (162.3 oz) with PW3390-03 Product warranty period 1 year Accessories Instruction Manual ×1, Measurement Guide ×1, Power cord ×1, USB cable (0.9 m	Power supply		
Mass 4.6 kg (162.3 oz) with PW3390-03 Product warranty period 1 year Accessories Instruction Manual ×1, Measurement Guide ×1, Power cord ×1, USB cable (0.9 m	Backup battery life	Clock, settings and integration values (Lithium battery), Approx. 10 years, @23°C (73°F)	
Product warranty period 1 year Accessories Instruction Manual ×1, Measurement Guide ×1, Power cord ×1, USB cable (0.9 m	Dimensions	340 mm (13.39 in) W × 170 mm (6.69 in) H × 156 mm (6.14 in) D (excluding protrusions)	
Accessories Instruction Manual ×1, Measurement Guide ×1, Power cord ×1, USB cable (0.9 m	Mass	4.6 kg (162.3 oz) with PW3390-03	
	Product warranty period	1 year	
	Accessories		

High Accuracy Sensor, Pass-Through Type

	AC/DC CURRENT SENSOR CT6862-05	AC/DC CURRENT SENSOR CT6863-05	AC/DC CURRENT SENSOR 9709-05	AC/DC CURRENT SENSOR CT6865-05
External Appearance				
Rated primary current	AC/DC 50 A rms	AC/DC 200 A rms	AC/DC 500 A rms	AC/DC 1000 A rms
Frequency band	DC to 1 MHz	DC to 500 kHz	DC to 100 kHz	DC to 20 kHz
Diameter of measurable conductors	φ 24 mm (0.94 in) or less	φ 24 mm (0.94 in) or less	φ 36 mm (1.42 in) or less	φ 36 mm (1.42 in) or less
Basic accuracy	For DC, 16 Hz to 400 Hz Amplitude: ±0.05% rdg. ±0.01% f.s. Phase: ±0.2° * No DC specifications	For DC, 16 Hz to 400 Hz Amplitude: ±0.05% rdg. ±0.01% f.s. Phase: ±0.2° * No DC specifications	For DC, 45 Hz to 66 Hz Amplitude: ±0.05% rdg. ±0.01% f.s. Phase: ±0.2° * No DC specifications	For DC, 16 Hz to 66 Hz Amplitude: ±0.05% rdg. ±0.01% f.s. Phase: ±0.2° * No DC specifications
Frequency characteristics (Amplitude)	to 100 kHz: ±2.0% rdg. ±0.05% f.s.	to 16 Hz: ±0.1% rdg. ±0.02% f.s. 400 Hz to 1 kHz: ±0.2% rdg. ±0.02% f.s. to 10 kHz: ±1.0% rdg. ±0.02% f.s. to 100 kHz: ±5.0% rdg. ±0.05% f.s. to 500 kHz: ±30% rdg. ±0.05% f.s.	to 45 Hz: ±0.2% rdg. ±0.02% f.s. 66 Hz to 500 Hz: ±0.2% rdg. ±0.02% f.s. to 5 kHz: ±0.5% rdg. ±0.05% f.s. to 10 kHz: ±2.0% rdg. ±0.05% f.s. to 10 kHz: ±2.0% rdg. ±0.05% f.s. to 10 kHz: ±3.0% rdg. ±0.10% f.s.	to 16 Hz: ±0.1% rdg, ±0.02% f.s. 66 Hz to 100 Hz: ±0.5% rdg, ±0.02% f.s. to 500 Hz: ±1.0% rdg, ±0.02% f.s. to 5 KHz: ±0.0% rdg, ±0.05% f.s. to 20 kHz: ±30% rdg, ±0.01% f.s.
Operating temperature range	-30°C to 85°C (-22°F to 185°F)	-30°C to 85°C (-22°F to 185°F)	0°C to 50°C (32°F to 122°F)	-30°C to 85°C (-22°F to 185°F)
Effect of conductor position	±0.01% rdg. or less (DC to 100 Hz)	±0.01% rdg. or less (DC to 100 Hz)	±0.05% rdg. or less (DC)	±0.05% rdg. or less (50/60 Hz)
Effects of external magnetic fields	In 400 A/m magnetic field (DC and 60 Hz) 10 mA or less	In 400 A/m magnetic field (DC and 60 Hz) 50 mA or less	In 400 A/m magnetic field (DC and 60 Hz) 50 mA or less	In 400 A/m magnetic field (DC and 60 Hz) 200 mA or less
Maximum rated voltage to ground	CAT III 1000 V	CAT III 1000 V	CAT III 1000 V	CAT III 1000 V
Output connector	HIOKI ME15W	HIOKI ME15W	HIOKI ME15W	HIOKI ME15W
Dimensions	70 mm (2.76 in) W x 100 mm (3.94 in) H x 53 mm (2.09 in) D, Cable length: 3 m (9.84 ft)	70 mm (2.76 in) W x 100 mm (3.94 in) H x 53 mm (2.09 in) D, Cable length: 3 m (9.84 ft)	160 mm (6.30 in) W x 112 mm (4.41 in) H x 50 mm (1.97 in) D, Cable length: 3 m (9.84 ft)	160 mm (6.30 in) W x 112 mm (4.41 in) H x 50 mm (1.97 in) D, Cable length: 3 m (9.84 ft)
Mass	Approx. 340 g (12.0 oz)	Approx. 350 g (12.3 oz)	Approx. 850 g (30.0 oz)	Approx. 980 g (34.6 oz)
Derating Characteristics	B00 H 80 B 00 D C 1 10 100 1k 10k 10k 1M Frequency [H2]	E 400 B 300 B 200 D C 1 10 100 1k 10k 100 k1 M Frequency [tz]	2000 200 2000 2	Terupon Ter

Custom cable lengths also available. Please inquire with your Hioki distributor.

High Accuracy Sensor, Clamp Type

	AC/DC CURRENT PROBE CT6841-05	AC/DC CURRENT PROBE CT6843-05	AC/DC CURRENT PROBE CT6844-05	AC/DC CURRENT PROBE CT6845-05	AC/DC CURRENT PROBE CT6846-05	
External Appearance						
Rated primary current	AC/DC 20 A rms	AC/DC 200 A rms	AC/DC 500 A rms	AC/DC 500 A rms	AC/DC 1000 A rms	
Frequency band	DC to 1 MHz	DC to 500 kHz	DC to 200 kHz	DC to 100 kHz	DC to 20 kHz	
Diameter of measurable conductors	φ 20 mm (0.79 in) or less (insulated conductor)	φ 20 mm (0.79 in) or less (insulated conductor)	φ 20 mm (0.79 in) or less (insulated conductor)	φ 50 mm (1.97 in) or less (insulated conductor)	φ 50 mm (1.97 in) or less (insulated conductor)	
Basic accuracy	For DC < f \leq 100 Hz Amplitude: $\pm 0.3\%$ rdg. $\pm 0.01\%$ f.s. Phase: $\pm 0.1^{\circ}$ For DC Amplitude: $\pm 0.3\%$ rdg. $\pm 0.05\%$ f.s.	For DC < f \leq 100 Hz Amplitude: $\pm 0.3\%$ rdg. $\pm 0.01\%$ f.s. Phase: $\pm 0.1^{\circ}$ For DC Amplitude: $\pm 0.3\%$ rdg. $\pm 0.02\%$ f.s.	For DC < f \leq 100 Hz Amplitude: $\pm 0.3\%$ rdg. $\pm 0.01\%$ f.s. Phase: $\pm 0.1^{\circ}$ For DC Amplitude: $\pm 0.3\%$ rdg. $\pm 0.02\%$ f.s.	For DC < f \leq 100 Hz Amplitude: $\pm 0.3\%$ rdg. $\pm 0.01\%$ f.s. Phase: $\pm 0.1^{\circ}$ For DC Amplitude: $\pm 0.3\%$ rdg. $\pm 0.02\%$ f.s.	For DC < f \leq 100 Hz Amplitude: $\pm 0.3\%$ rdg. $\pm 0.01\%$ f.s. Phase: $\pm 0.1^{\circ}$ For DC Amplitude: $\pm 0.3\%$ rdg. $\pm 0.02\%$ f.s.	
Frequency characteristics (Amplitude)	to 10 kHz: ±1.5% rdg. ±0.02% f.s.	to 500 Hz: ±0.3% rdg. ±0.02% f.s. to 1 kHz: ±0.5% rdg. ±0.02% f.s. to 10 kHz: ±1.5% rdg. ±0.02% f.s. to 50 kHz: ±5.0% rdg. ±0.02% f.s. to 50 kHz: ±30% rdg. ±0.05% f.s.	$\begin{array}{llllllllllllllllllllllllllllllllllll$	to 1 kHz: ±0.5% rdg. ±0.02% f.s.	to 500 Hz: ±0.5% rdg. ±0.02% f.s. to 1 kHz: ±1.0% rdg. ±0.02% f.s. to 5 kHz: ±2.0% rdg. ±0.02% f.s. to 10 kHz: ±5.0% rdg. ±0.05% f.s. to 20 kHz: ±30% rdg. ±0.10% f.s.	
Operating temperature range	-40°C to 85°C (-40°F to 185°F)	-40°C to 85°C (-40°F to 185°F)	-40°C to 85°C (-40°F to 185°F)	-40°C to 85°C (-40°F to 185°F)	-40°C to 85°C (-40°F to 185°F)	
Effect of conductor position	±0.1% rdg. or less (DC to 100 Hz)	±0.1% rdg. or less (DC to 100 Hz)	±0.1% rdg. or less (DC to 100 Hz)	±0.2% rdg. or less (DC to 100 Hz)	±0.2% rdg. or less (50 Hz/60 Hz)	
Effects of external magnetic fields	In 400 A/m magnetic field (DC and 60 Hz) under 50 mA	In 400 A/m magnetic field (DC and 60 Hz) under 50 mA	In 400 A/m magnetic field (DC and 60 Hz) under 100 mA	In 400 A/m magnetic field (DC and 60 Hz) under 150 mA	In 400 A/m magnetic field (DC and 60 Hz) under 150 mA	
Output connector	HIOKI ME15W	HIOKI ME15W	HIOKI ME15W	HIOKI ME15W	HIOKI ME15W	
Dimensions	153 mm (6.02 in) W x 67 mm (2.64 in) H x 25 mm (0.98 in) D Cable length: 3 m (9.84 ft)	153 mm (6.02 in) W x 67 mm (2.64 in) H x 25 mm (0.98 in) D Cable length: 3 m (9.84 ft)	153 mm (6.02 in) W x 67 mm (2.64 in) H x 25 mm (0.98 in) D Cable length: 3 m (9.84 ft)	238 mm (9.37 in) W x 116 mm (4.57 in) H x 35 mm (1.38 in) D Cable length: 3 m (9.84 ft)	238 mm (9.37 in) W x 116 mm (4.57 in) H x 35 mm (1.38 in) D Cable length: 3 m (9.84 ft)	
Mass	350 g (12.3 oz)	370 g (13.1 oz)	400 g (14.1 oz)	860 g (30.3 oz)	990 g (34.9 oz)	
Derating Characteristics	Tic Ambient temperature -40°C (-40°F) < TA < 60°C (140°F) -40°C (-40°F) < TA < 60°C (140°F) < TA < 60°C	Tr. Ambient temperature -40°C (-40°F) = TA ≤ 40°C (-104°F) -40°C (-104°F) = TA ≤ 40°C (-104°F) -40°C (-104°F) = TA ≤ 60°C (-104°F) -40°C (-40°F) = TA ≤ 80°C (-104°F) -40°C (-40°F) = TA ≤ 80°C (-105°F) -40°C (-40°F) = TA ≤ 40°C (-105°F) -40°C (-105°F) = TA ≤ 40°C (-105°F) = TA ≤ 40°C (-105°F) -40°C (-105°F) = TA ≤ 40°C (-105°F)	500 500 100 100 100 100 100 100	Th: Ambient temperature Th: Ambient temperatu		

Custom cable lengths also available. Please inquire with your Hioki distributor.

High Accuracy Sensor, Direct Wire Type

	AC/DC CURRENT BOX PW9100-03	AC/DC CURRENT BOX PW9100-04	
External Appearance	in in in	in in in in	
Number of input channels	3ch	4ch	
Rated primary current	AC/DC	50 A rms	
Frequency band	DC to 3.5 M	MHz (-3 dB)	
Measurement terminals	Terminal block (with sa	afety cover), M6 screws	
Basic accuracy	For 45 Hz to 65 Hz Amplitude: ±0.02% rdg. ±0.005% f.s. For DC Amplitude: ±0.02% rdg. ±0.007% f.s.		
Frequency characteristics (Amplitude)	to 1 kHz: ±0.1% to 50 kHz: ±1% r to 100 kHz: ±2% i to 1 MHz: ±10%	6 rdg. ±0.02% f.s. 6 rdg. ±0.01% f.s. dg. ±0.02% f.s. rdg. ±0.05% f.s. rdg. ±0.05% f.s. Typical	
Input resistance	1.5 mΩ or less	s (50 Hz/60 Hz)	
Operating temperature range	0°C to 40°C (32°F to 104°F)		
Effects of common- mode voltage (CMRR)		er 100 kHz 120 dB or greater e/common-mode voltage)	
Maximum rated voltage to ground	1000 V (Measurement category II),	, 600 V (Measurement category III), t overvoltage 6000 V	
Output connector	HIOKI	ME15W	
Dimensions		3.46 in) H x 260 mm (10.24 in) D, 0.8 m (2.62 ft)	
Mass	3.7 kg (130.5 oz)	4.3 kg (151.7 oz)	
Derating Characteristics	The second secon		

Newly developed DCCT method allows world-class measurement range and measurement accuracy at a rating of 50 A. (5 A rating version also available. Please inquire with your Hioki



Wiring connection example 2 - Introducing a new and innovative measuring method

Shorten the wiring for current measurement by installing the PW9100 close to the measurement target. This will also keep the effects of wiring resistance, capacity coupling and other objective factors on the measured values to a minimum.



CLAMP ON SENSOR 9272-05 AC 200 A rms/20 A rms switching 1 kHz to 100 kHz φ 46 mm (1.81 in) or less For 45 Hz to 66 Hz Amplitude: ±0.3% rdg. ±0.01% f.s. Phase:±0.2 ° ±2.0% rdg. ±0.10% f.s. ±0.5% rdg. ±0.02% f.s. ±2.5% rdg. ±0.02% f.s. ±5% rdg. ±0.1% f.s. ±30% rdg. ±0.1% f.s. to 10 Hz: to 45 Hz: 66to 10 kHz: to 50 kHz to 100 kHz:

0°C to 50°C (32°F to 122°F) ±0.2% rdg. or less (60 Hz)

In 400 A/m magnetic field (60 Hz) under 100 mA

HIOKI ME15W

78 mm (3.07 in) W x 188 mm (7.40 in) H x 35 mm (1.38 in) D Cable length: 3 m (9.84 ft) 450 g (15.9 oz)



Standard Sensor

	AC/DC CURRENT SENSOR CT7642 AC/DC AUTO ZERO CURRENT SENSOR CT7742	AC FLEXIBLE CURRENT SENSOR CT7044, CT7045, CT7046	
External Appearance			
Rated primary current	AC/DC 2000 A rms	AC 6000 A rms	
Frequency band	CT7642: DC to 10 kHz CT7742: DC to 5 kHz	10 Hz to 50 kHz (±3 dB)	
Diameter of measurable conductors	φ 55 mm (2.17 in) or less	CT7044: φ 100 mm (3.94 in) or less CT7045: φ 180 mm (7.09 in) or less CT7046: φ 254 mm (10.00 in) or less	
Basic accuracy	For DC, 45 Hz to 66 Hz Amplitude: ±1.5% rdg. ±0.5% f.s. For up to 66 Hz Phase:±2.3 °	For 45 to 66 Hz, with flexible cable core Amplitude: ±1.5% rdg. ±0.25% f.s. Phase:±1.0 °	
Frequency characteristics (Amplitude)	66 kHz to 1 kHz ±2.5% rdg. ±1.0% f.s.	-	
Operating temperature range	-25°C to 65°C (-13°F to 149°F)	-25°C to 65°C (-13°F to 149°F)	
Effect of conductor position	±1.0% rdg. or less	±3.0% or less	
Effects of external magnetic fields	In 400 A/m magnetic field (DC) 0.2% f.s. or less	In 400 A/m magnetic field (50 Hz/60 Hz) CT7044, CT7045: 1.25% f.s. or less CT7046: 1.5% f.s. or less	
Output connector	HIOKI PL14*	HIOKI PL14*	
Dimensions	64 mm (2.52 in) W x 195 mm (7.68 in) H x 34 mm (1.34 in) D Cable length: 2.5 m (8.20 ft)	Circuit box: 25 mm (0.98 in) W x 72 mm (2.83 in) H x 20 mm (0.79 in) D Cable length: 2.5 m (8.20 ft)	
Mass	510 g (18.0 oz)	CT7044: 160 g (5.6 oz) CT7045: 174 g (6.1 oz) CT7046: 186 g (6.6 oz)	
Derating Characteristics	2.5 k 2.5 k 2.	12 k 12 k 10 k 6 k 0 k 0 k 10	

Current Summing

	SENSOR UNIT CT9557	
	FRONT	
External Appearance	Sensor input	
	REAR	
	Summed waveform output (CT9904 connected)	
Connectable current sensor	Current sensor with HIOKI ME15W (male) on the output connector	
Summed waveform output accuracy	DC: ±0.06% rdg.±0.03% f.s. to 1 kHz: ±0.06% rdg.±0.03% f.s. to 10 kHz: ±0.10% rdg.±0.03% f.s. to 10 kHz: ±0.20% rdg.±0.10% f.s. to 100 kHz: ±0.20% rdg.±0.10% f.s. to 300 kHz: ±1.0% rdg.±0.20% rdg.t.s. to 700 kHz: ±5.0% rdg.±0.20% f.s. to 11 MHz: ±10.% rdg.±0.50% f.s.	
Operating temperature range	-10°C to 50°C (14°F to 122°F)	
Power supply	AC ADAPTER Z1002 (100 to 240 V AC, 50/60 Hz, Max. rated power when in combination with other units: 155 VA) External power supply (10 to 30 V DC, Max. rated power: 60 VA)	
Output connector	HIOKI ME15W (male)*	
External dimensions	116 mm (4.57 in) W x 67 mm (2.64 in) H x 132 mm (5.20 in) D	
Mass	420 g (14.8 oz)	
Accessories	AC ADAPTER Z1002, Power cord, Instruction Manual	

* CT9904 (sold separately) is required to connect to PW3390

* CT9920 (sold separately) is required to connect PW3390 to the sensor with HIOKI PL14 on the output connector.

Model : POWER ANALYZER PW3390

Model No. (Order Code)	D/A output	Motor analysis
PW3390-01	-	-
PW3390-02	0	-
PW3390-03	0	0

Accessories: Instruction Manual ×1, Measurement Guide ×1, Power cord ×1, USB cable ×1, Input cord label ×2, D-sub 25-pin connector ×1 (PW3390-02, PW3390-03)

. The optional voltage cord and current sensor are required for taking measurements.

• Motor analysis and D/A output cannot be changed or added after delivery

Current Measurement Options

Name (Note)	Model No. (Order Code)
AC/DC CURRENT SENSOR (50 A)	CT6862-05
AC/DC CURRENT SENSOR (200 A)	CT6863-05
AC/DC CURRENT SENSOR (500 A)	9709-05
AC/DC CURRENT SENSOR (1000 A)	CT6865-05
AC/DC CURRENT PROBE (20 A)	CT6841-05
AC/DC CURRENT PROBE (200 A)	CT6843-05
AC/DC CURRENT PROBE (500 A, φ 20 mm (0.79 in))	CT6844-05
AC/DC CURRENT PROBE (500 A, φ 50 mm (1.97 in))	CT6845-05
AC/DC CURRENT PROBE (1000 A)	CT6846-05
CLAMP ON SENSOR (AC 20 A/200 A)	9272-05
AC/DC CURRENT BOX (50 A, 3 ch)	PW9100-03
AC/DC CURRENT BOX (50 A, 4 ch)	PW9100-04
AC/DC AUTO ZERO CURRENT SENSOR (2000 A)	CT7742 *
AC/DC CURRENT SENSOR (2000 A)	CT7642 *
AC FLEXIBLE CURRENT SENSOR (6000 A, \$\$\phi\$ 100 mm (3.94 in))	CT7044 *
AC FLEXIBLE CURRENT SENSOR (6000 A, ¢ 180 mm (7.09 in))	CT7045 *
AC FLEXIBLE CURRENT SENSOR (6000 A, ¢ 254 mm (10.00 in))	CT7046 *
SENSOR UNIT (Sensor power supply with 4 channel summing function)	CT9557 **

* CONVERSION CABLE CT9920 is required to connect to PW3390. ** CONNECTION CABLE CT9904 is required to connect to PW3390.

Voltage Measurement Options

VOLTAGE CORD L9438-50

VOLTAGE CORD L1000

1 WIRING ADAPTER PW9000

Connection Options

CONNECTION CORD L9217

CONNECTION CABLE 9683

(9.84 ft)

Red, black: 1 each 1000 V specification. Cord length: 3 m (9.84 ft) CAT IV 600 V. CAT III 1000 V

Red, yellow, blue, gray: 1 each; Black: 4 1000 V specification, Cord length: 3 m

CAT IV 600 V, CAT III 1000 V

When making a 3-phase 3-wire

voltage cords from 6 to 3.

BNC-BNC. For motor analysis input Cable length: 1.6 m (5.25 ft)

(3P3W3M) connection, this product allows you to reduce the number of

For synchronous measurement,

Cable length: 1.5 m (4.92 ft)



Red, black: 1 each, With connector, Cable length: 1.5 m (4.92 ft) For extension of L9438-50 or L1000 CAT IV 600 V. CAT III 1000 V

GRABBER CLIP 9243





connection, this product allows you to reduce the number of voltage cords from 6 to 4.

LAN CABLE 9642 Supplied with straight to cross conversion connector, Cable length: 5 m (16.41 ft)

RS-232C CABLE 9637 9pin-9pin cross Cable length: 1.8 m (5.91 ft)

CONVERSION CABLE CT9900

Required to connect PW3390 to the current sensor with HIOKI PL23 on the output connector.

[Applicable products] CT6841, CT6843, CT6844, CT6845, CT6846, CT6862, CT6863, 9709, CT6865, 9272-10

CONVERSION CABLE CT9920



Required to connect PW3390 to the current sensor with HIOKI PL14 on the output connector.

[Applicable products] CT7742, CT7642, CT7044, CT7045, CT7046

CONNECTION CABLE CT9904



Cable length: 1 m (3.28 ft) Required to connect the summing waveform output terminal of CT9557 to PW3390. [Applicable products] CT9557

Built-To-Order (Current Measurement)

PW9100 5A-rated model 9709-05 high-accuracy model CT6862-05 high-accuracy model CT6863-05 high-accuracy model

Please contact your Hioki distributor or subsidiary for more information.

AC/DC 2000 A high accuracy sensor, pass-through type

Other Options

PC CARD 512 MB 9728 PC CARD 1 GB 9729 PC CARD 2 GB 9830



Use only PC Cards sold by HIOKI. Compatibility and performance are not guaranteed for PC cards made by other manufacturers. You may be unable to read from or save data to such cards.

CARRYING CASE 9794



Carrying Case for PW3390 and 3390 448 mm (17.64 in) W x 618 mm (24.33 in) H x 295 mm (11.61 in) D

Rackmount fittings

D-sub 25-pin - BNC (male) 16 ch conversion, Cord length: 2.5 m (8.20 ft)

Built-To-Order (Other)

D/A output cable

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